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INSTITUTO NACIONAL DE PESQUISAS ESPACIAIS

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XXXVII CONGRESSO NACIONAL DE MATEMÁTICA
APLICADA E COMPUTACIONAL

CNMAC 2017

Matemática Aplicada e Computacional acelerando
o desenvolvimento do país - São José dos Campos - SP

Inverse Problems in Space Research Methods and Applications

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Inverse problems

Methods

- Optimization problem with constraints:
 - Deterministic optimizer: Quasi-Newton
 - Deterministic optimizer: variational approach
- Optimization problem with constraints:
 - Stochastic optimizer: Ant Colony System
 - Stochastic optimizer: Multi-Particle Collision Algorithm
- Optimization problem: hybrid methods
- Artificial neural networks

Inverse problems

Optimization problem with constrains

$$J_\alpha(f) = \left\| A(f) - \theta^\delta \right\|_2^2 + \alpha \Omega[f]$$

$$\Omega[f] = \sum_{k=0}^p \mu_k \left\| f^{(k)} \right\|_2^2 \quad (\text{Tikhonov})$$

$$\Omega(f) = \sum_{q=1}^p s_q \log(s_q), \quad \text{with: } s_q = r_q^{(k)} / \sum_{q=1}^N r_q^{(k)} \quad (\text{Entropy})$$

$$r_q^{(k)} = \begin{cases} f_q & \text{for } k = 0 \\ f_{q+1} - f_q + (f_{\max} - f_{\min}) + \zeta & \text{for } k = 1 \\ f_{q+1} - 2f_q + f_{q-1} + 2(f_{\max} - f_{\min}) + \zeta & \text{for } k = 2 \end{cases}$$

Inverse problems

Deterministic: Quasi-Newton

1. Solve the direct problem for \mathbf{f}^n and compute the objective function $M^\alpha(\mathbf{f}^n)$.
2. Compute by finite differences the gradient $\nabla M^\alpha(\mathbf{f}^n)$.
3. Compute a positive-definite quasi-Newton approximation to the Hessian \mathbf{H}^n :

$$\mathbf{H}^n = \mathbf{H}^{n-1} + \frac{\mathbf{b}^n (\mathbf{b}^n)^T}{(\mathbf{b}^n)^T \mathbf{u}^n} - \frac{\mathbf{H}^{n-1} \mathbf{u}^n (\mathbf{u}^n)^T \mathbf{H}^{n-1}}{(\mathbf{u}^n)^T \mathbf{H}^{n-1} \mathbf{u}^n},$$

where: $\mathbf{b}^n = \mathbf{f}^n - \mathbf{f}^{n-1}$,
 $\mathbf{u}^n = \nabla M^\alpha(\mathbf{f}^n) - \nabla M^\alpha(\mathbf{f}^{n-1})$.

4. Compute the search direction \mathbf{d}^n as a solution of the following quadratic programming subproblem:

$$\text{Minimize } [\nabla M^\alpha(\mathbf{f}^n)]^T \mathbf{d}^n + \frac{1}{2} (\mathbf{d}^n)^T (\mathbf{H}^n) \mathbf{d}^n \text{ subjected to } l_q - p_q^n \leq d_q \leq u_q - p_q^n.$$

5. Set $\mathbf{f}^{n+1} = \mathbf{f}^n + \beta^n \mathbf{d}^n$, where the step length β^n minimizes $M^\alpha(\mathbf{f}^n + \beta^n \mathbf{d}^n)$.
6. Test the convergence; stop or return to step 1.

Inverse problems

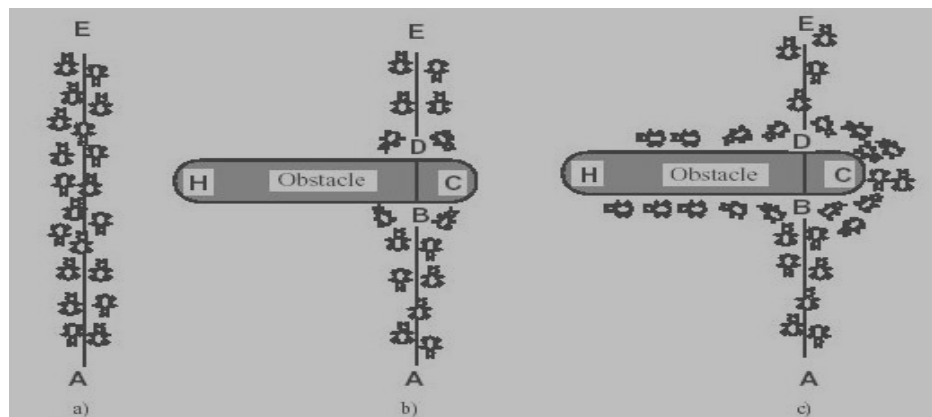
Deterministic: Variational approach

- Step 1:* Choose an initial guess \mathbf{K}^0 .
- Step 2:* Solve the direct problem, Eqs. (1)–(2), to obtain $\mathbf{x}(t)$.
- Step 3:* Solve the adjoint problem, Eqs. (15)–(16), to obtain the *Lagrange* multiplier vector $\boldsymbol{\lambda}(t)$.
- Step 4:* Knowing $\boldsymbol{\lambda}(t)$, compute the gradient function vector $\mathbf{J}'[\mathbf{K}]$ from Eq. (19).
- Step 5:* Compute the conjugate coefficient vector $\boldsymbol{\gamma}^n$ from Eq. (22).
- Step 6:* Compute the direction of descent vector \mathbf{P}^n from Eq. (21).
- Step 7:* Set $\Delta\mathbf{K} = \mathbf{P}^n$ [14], and solve the sensitivity problem, Eqs. (10)–(11), to obtain $\Delta\mathbf{x}(t)$.
- Step 8:* Compute the step size vector $\boldsymbol{\beta}^n$ from Eq. (24).
- Step 9:* Compute \mathbf{K}^{n+1} from Eq. (20).
- Step 10:* Test if the stopping criteria, Eq. (28), is satisfied. If not, go to step 2.

Inverse problems

ACS (Ant Colony System)

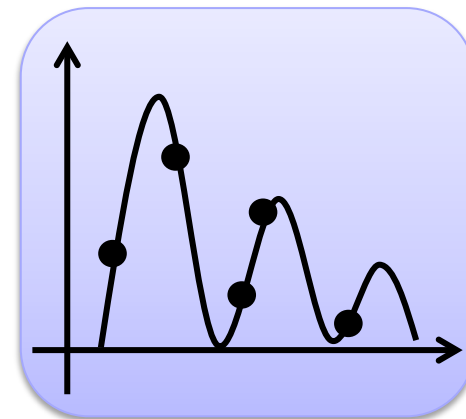
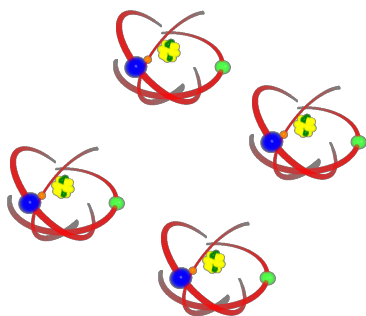
- Ant: a candidate solution
- For each iteration: the best ant is selected
- After iterations, “best of the bests” ant is chosen!
- Modified ACS: only 10% smoothers (2nd-order Tikhonov) of the ant population are selected



Inverse problems

MPCA (Multi-Particle Colisium Algorithm)

- Particle: a candidate solution
- Neutron traveling inside a nuclear reactor
- Two phenomena: absorption and scattering
- Multi-particle: several particles in cooperation



Inverse problems

Available for download:

www.epacis.net/jcis/PDF_JCIS/JCIS11-art.01.pdf



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A new multi-particle collision algorithm for optimization in a high performance environment

Eduardo Fávero Pacheco da Luz, José Carlos Becceneri and Haroldo Fraga de Campos Velho

Manuscript received on July 31, 2008 / accepted on October 5, 2008



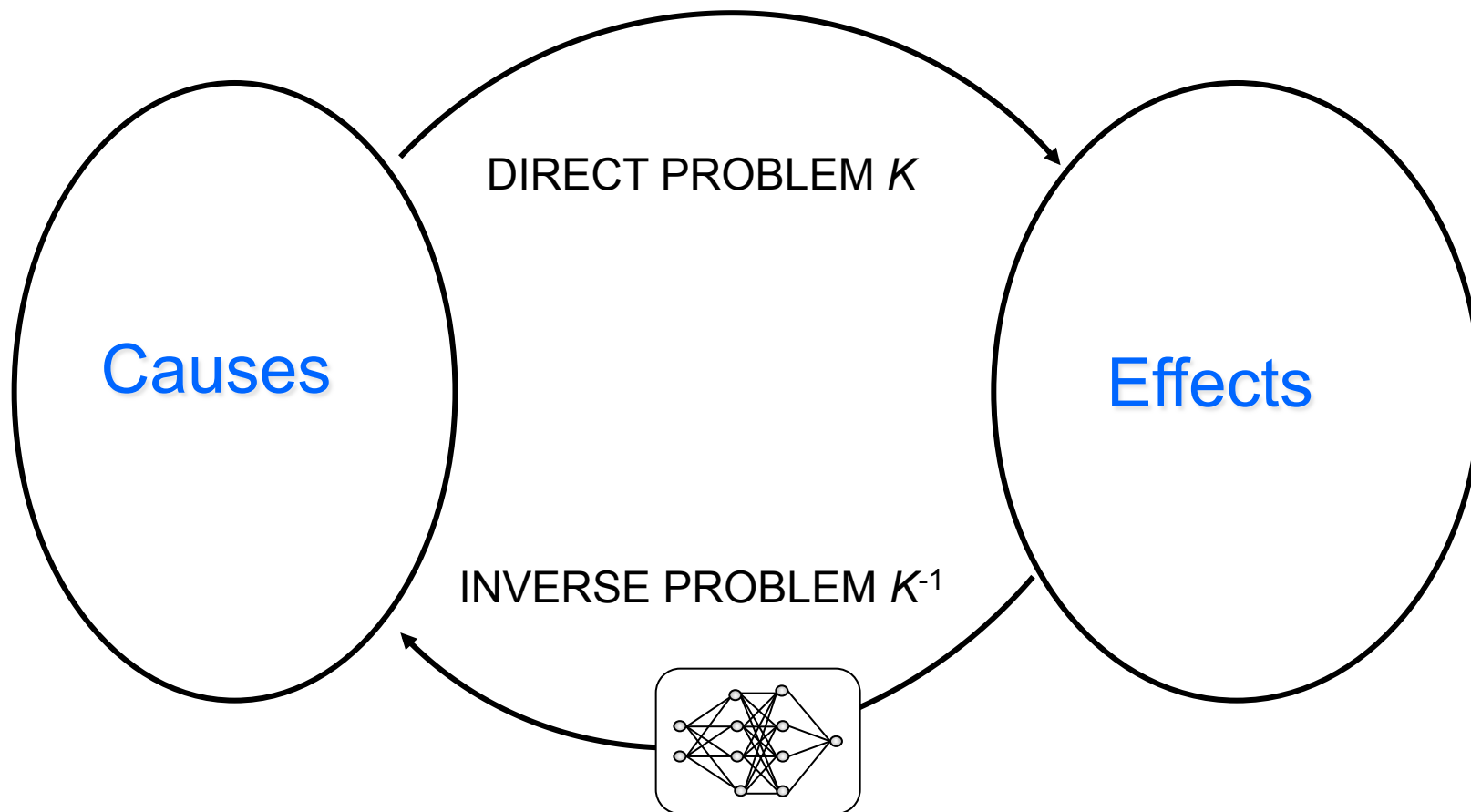
Inverse problems

Meta-heuristics for inverse problems



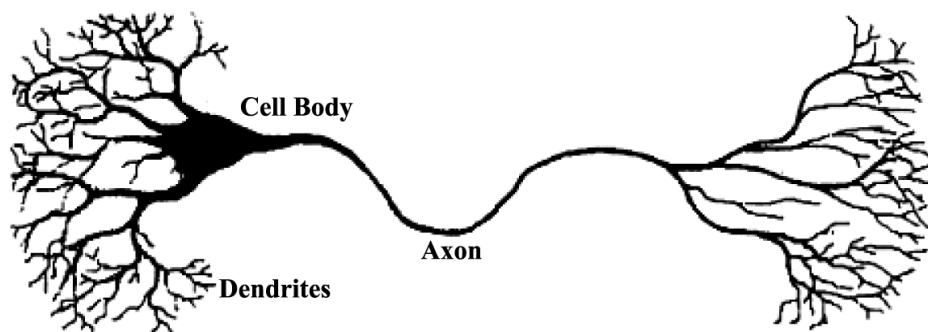
Inverse problems

Neural networks for inverse problems

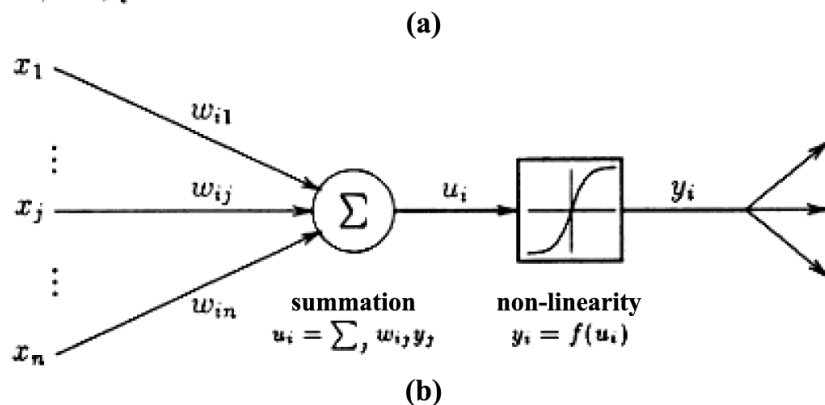


Inverse problems

Neural networks for inverse problems



Biological neuron



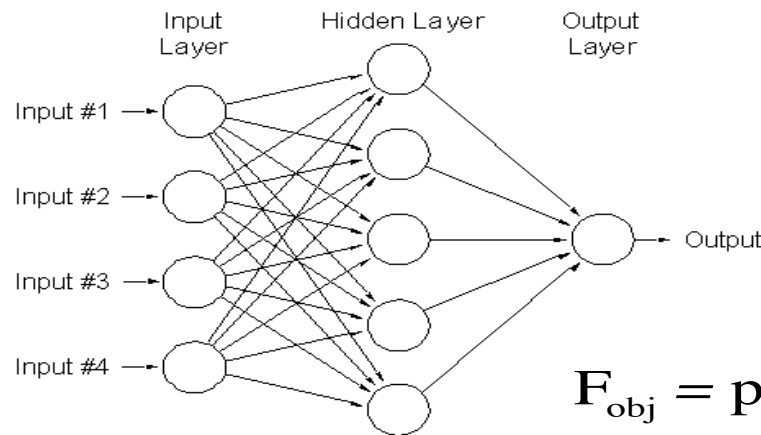
Artificial neuron

$$u_i = f\left(\sum w_{ij} x_j + b_j\right)$$

$$y_i = \varphi(u_i)$$

Inverse problems

Optimal neural network for IP



$$F_{\text{obj}} = \text{penality} * \frac{(\rho_1 * E_{\text{train}} + \rho_2 * E_{\text{activ}})}{\rho_1 + \rho_2}$$

$$\text{penality} = \underbrace{\left(c_1 * \left(e^{\#\text{neuron}} \right)^2 \right)}_{\text{complexity factor-1}} \times \underbrace{\left(c_2 * (\#\text{epoch}) \right)}_{\text{complexity factor-2}} + 1$$

Inverse problems

Optimal neural network for IP

$$F_{\text{obj}} = \text{penalty} * \frac{(\rho_1 * E_{\text{train}} + \rho_2 * E_{\text{activ}})}{\rho_1 + \rho_2}$$

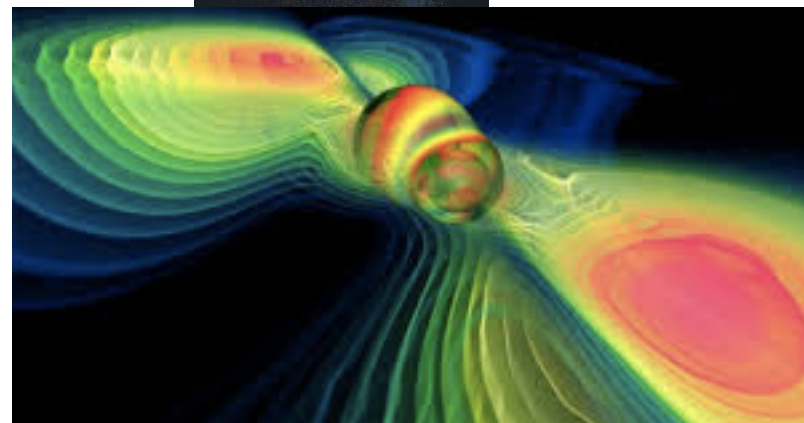
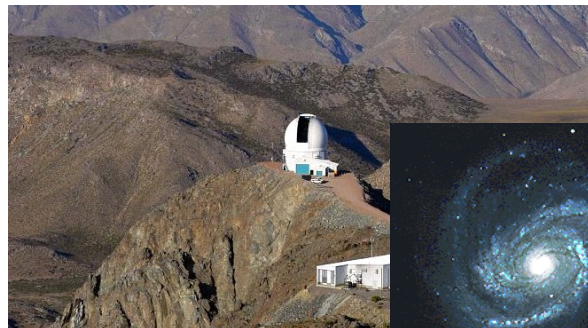
Parameters	Value
# hidden layer	1 2 3
# neurons	1 ... 32
Learning rate	0 ... 1
Momentum	0 ... 0.9
Activation function	hiperbolic tangente Logistic Gaussian

Optimization by MPCA



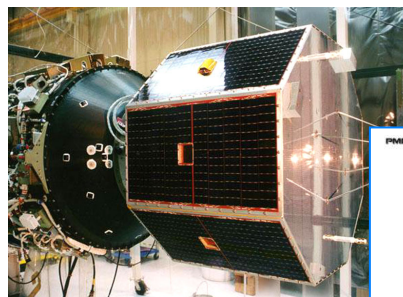
Space Research: Four Pillars

- Space Science
- Space Engineering
- Space Applications
- Space Health/Medicine (*)



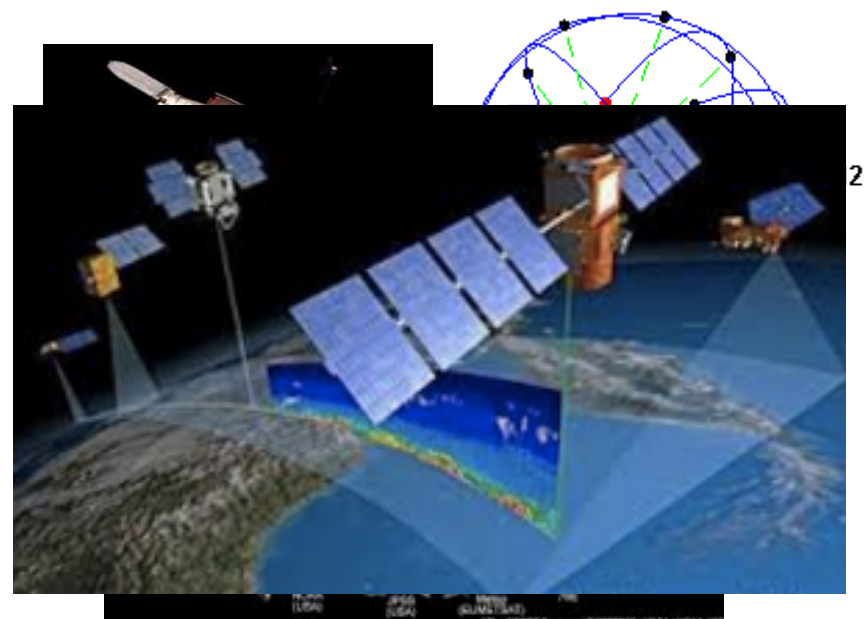
Space Research: four pillars

- Space Science
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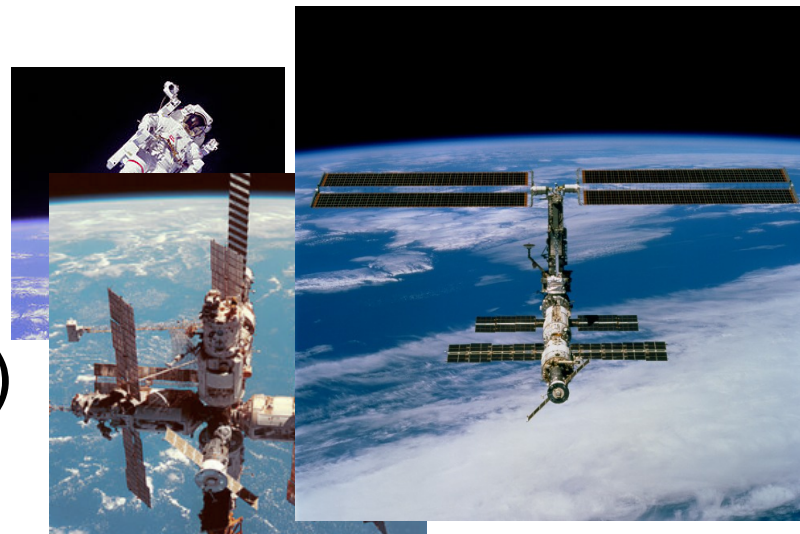
Space Research: four pillars

- Space Science
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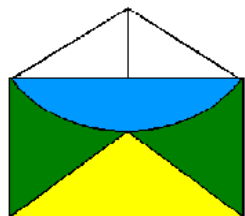


Space Research: four pillars

- Space Science
- Space Engineering
- Space Applications
- Space Health/Medicine (*)



Space Research (Space Science)



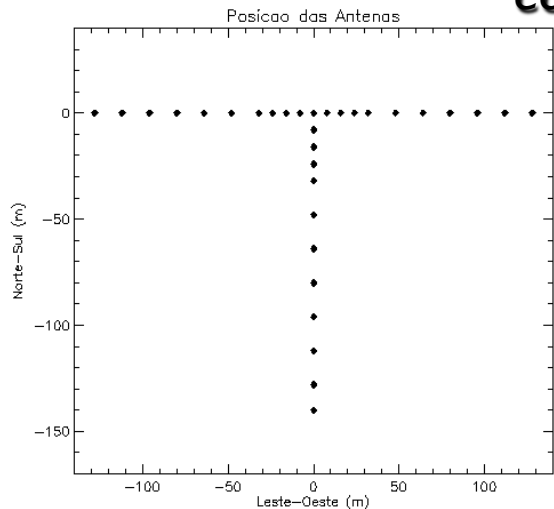
BRAZILIAN
DECIMETRIC
ARRAY

B D A



Space Research (Space Science)

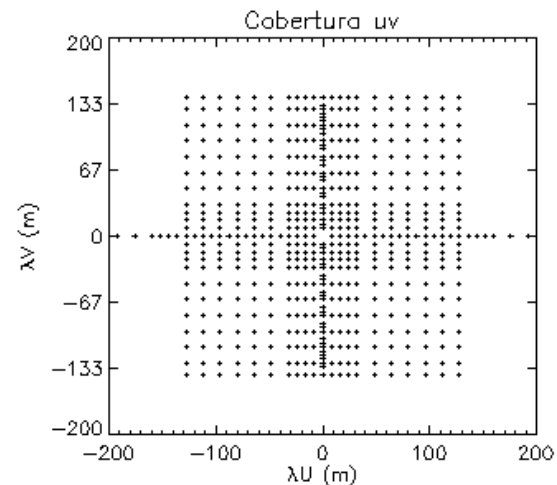
configuration



correlation

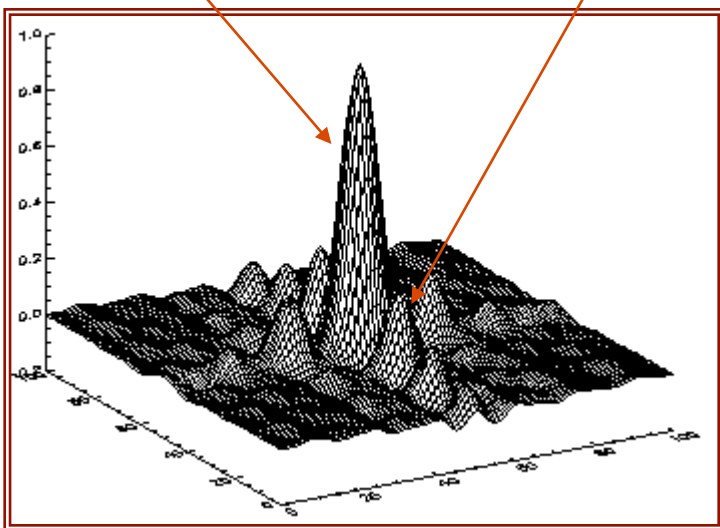


samples



Central peak

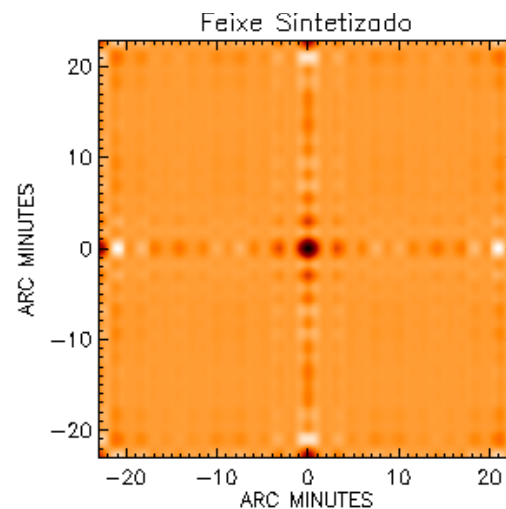
Secondary peaks



Synthesized beam



Fourier⁻¹

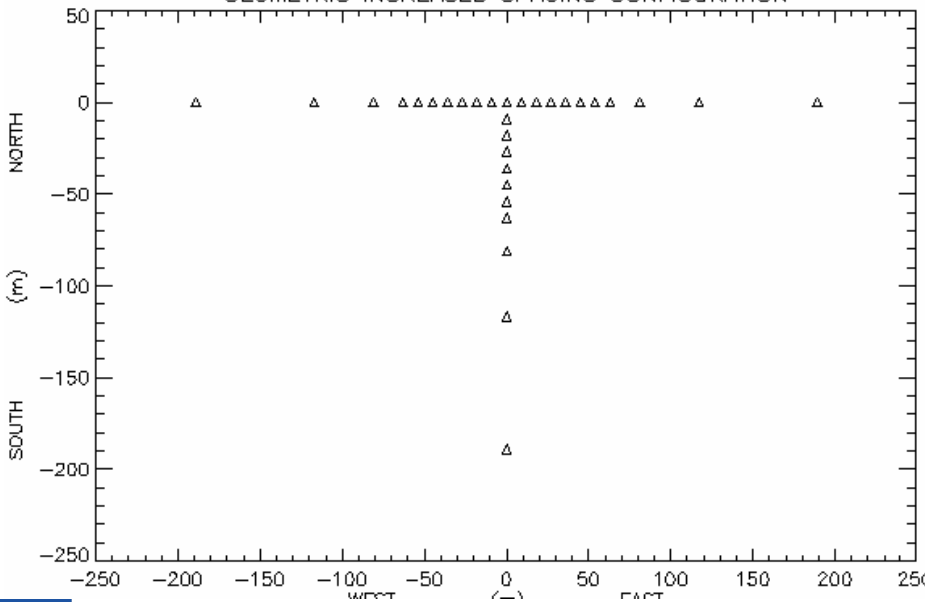


Space Research (Space Science)

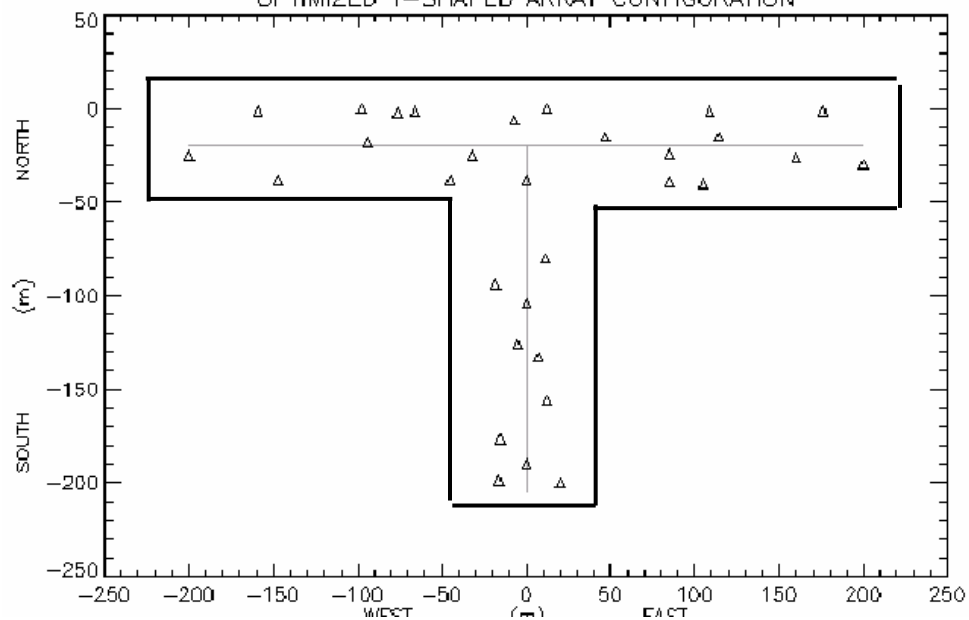
Objective function:

$$J(\chi) = \sum_m \sum_n q_{mn} \log(q_m) \quad \text{with} \quad q_{mn} = \frac{B_{mn}}{\sum_i \sum_j B_{ij}}$$

GEOMETRIC INCREASED SPACING CONFIGURATION



OPTIMIZED T-SHAPED ARRAY CONFIGURATION

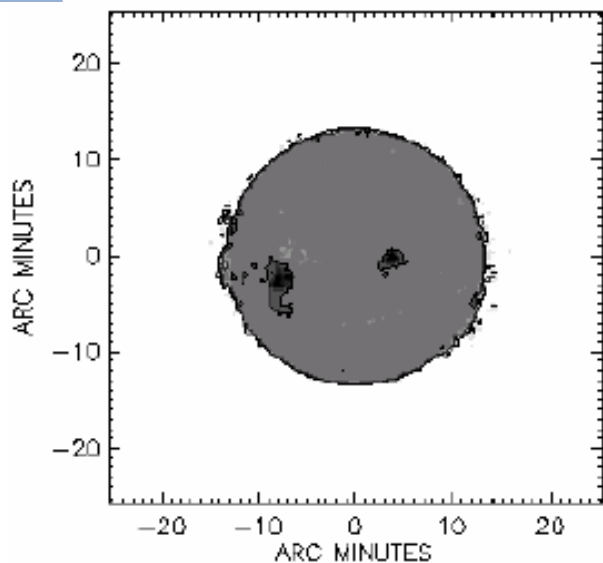


Optimizer: ACO (Ant Colony Optimization)

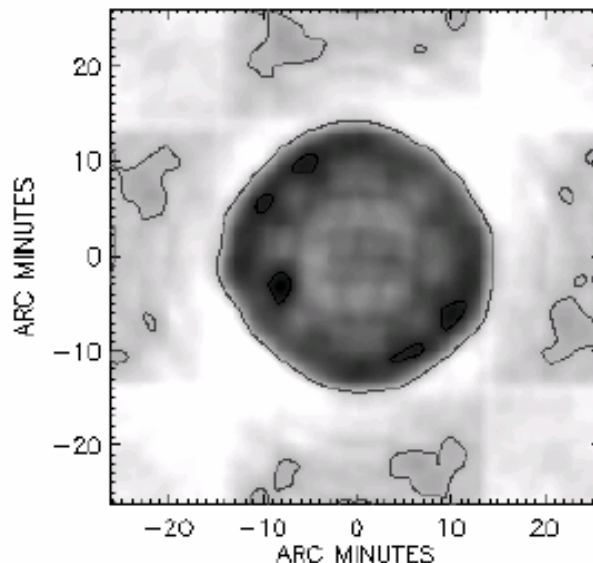
Space Research (Space Science)

Images for radio-interferometric telescope

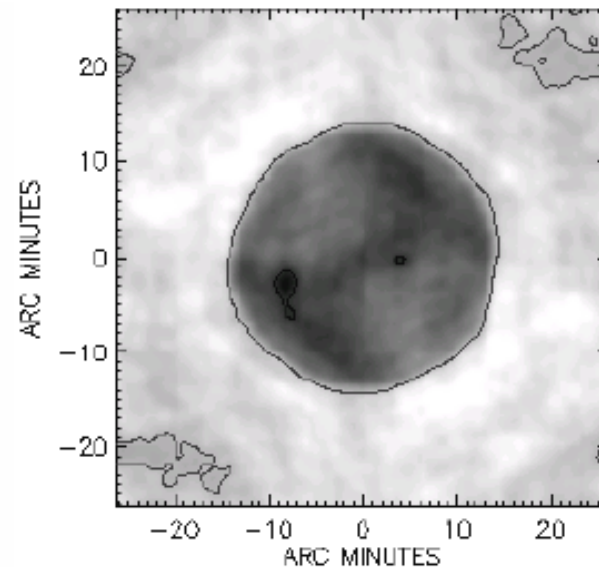
True



T-thin

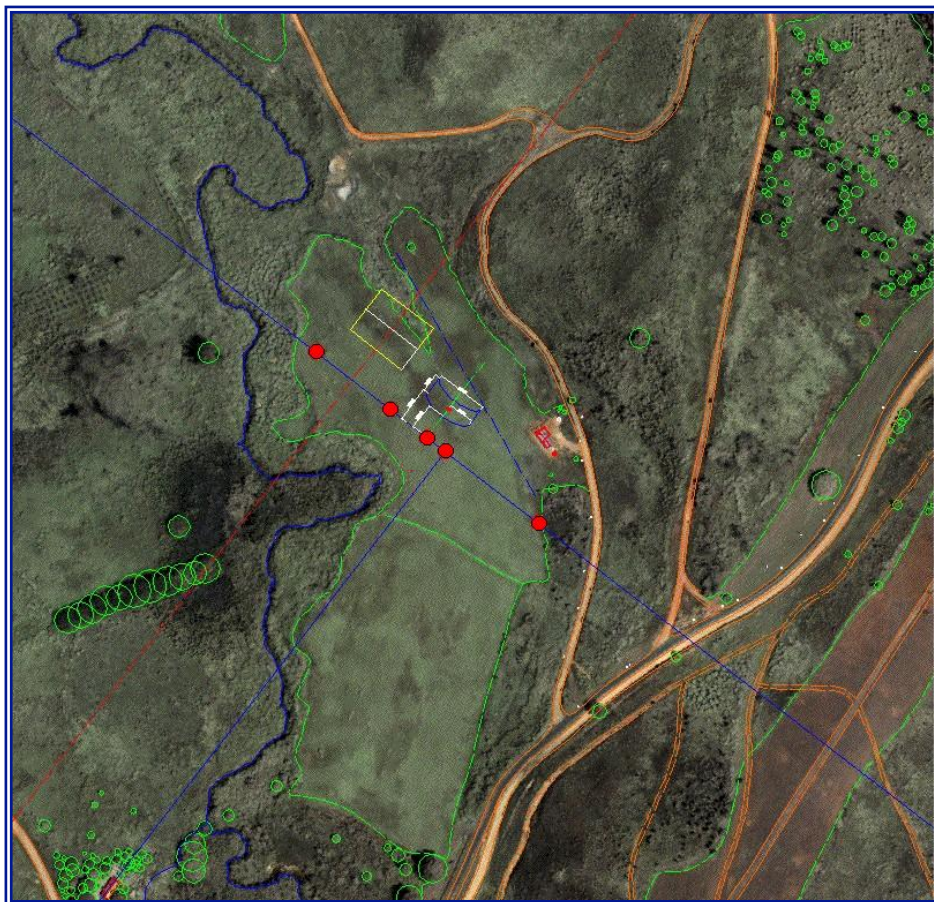


T-fat (optimized)

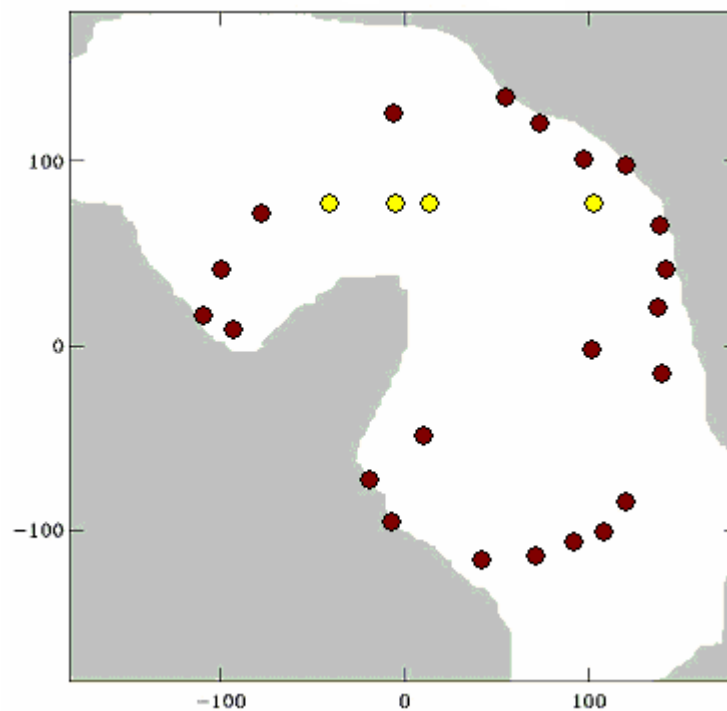


Space Research (Space Science)

Welcome to the real world!



Final optimized configuration



Space Research (Space Science)

Magneto-telluric inversion

Eqs. Maxwell 2D :

$$\begin{aligned}\vec{\nabla} \times \vec{H} &= 4\pi\sigma \vec{E} \\ \vec{\nabla} \times \vec{E} &= 4\pi\sigma \vec{H}\end{aligned}$$

$H=H(y,z)$ magnetic field
 $E=E(y,z)$ electric field

$$\left\{ \begin{aligned}\frac{\partial H_z}{\partial y} - \frac{\partial H_y}{\partial z} &= 4\pi\sigma E_x \\ \frac{\partial H_x}{\partial z} &= 4\pi\sigma E_y \\ -\frac{\partial H_x}{\partial y} &= 4\pi\sigma E_z\end{aligned}\right.$$

$$\left\{ \begin{aligned}\frac{\partial E_z}{\partial y} - \frac{\partial E_y}{\partial z} &= 4\pi\sigma H_x \\ \frac{\partial E_x}{\partial z} &= -i\omega H_y \\ -\frac{\partial E_x}{\partial y} &= -i\omega H_z\end{aligned}\right.$$

$$\left\{ \begin{aligned}\nabla^2 H_x &= \frac{\partial^2 H_x}{\partial y^2} + \frac{\partial^2 H_x}{\partial z^2} = i\eta^2 H_x \\ -\frac{\partial H_x}{\partial y} &= 4\pi\sigma E_z ; \frac{\partial H_x}{\partial z} = 4\pi\sigma E_y\end{aligned}\right.$$

$$\left\{ \begin{aligned}\nabla^2 E_x &= \frac{\partial^2 E_x}{\partial y^2} + \frac{\partial^2 E_x}{\partial z^2} = i\eta^2 E_x \\ -\frac{\partial E_x}{\partial y} &= -i\omega H_z ; \frac{\partial E_x}{\partial z} = -i\omega H_y\end{aligned}\right.$$

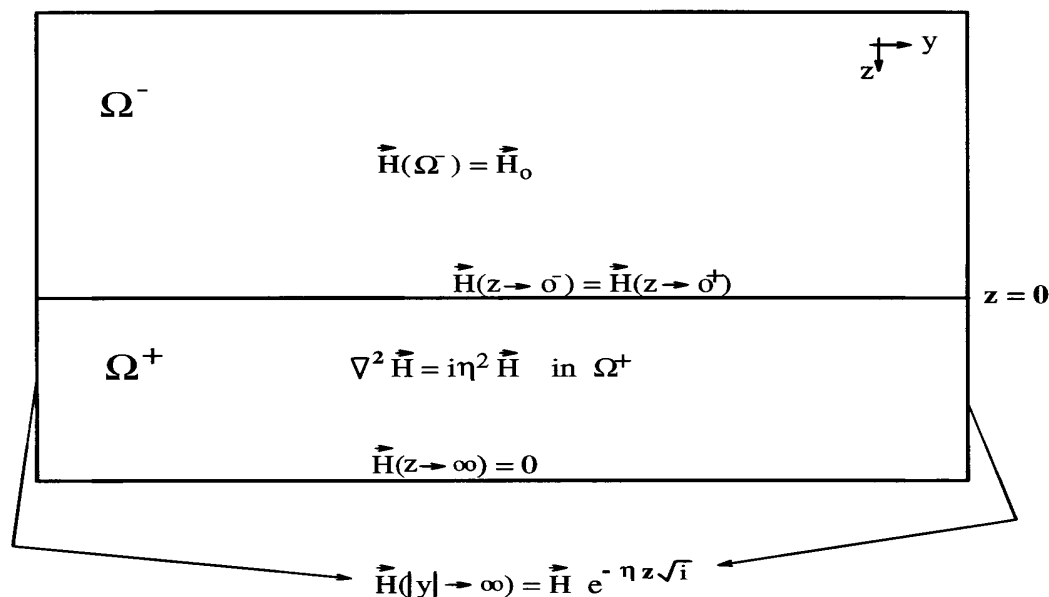
Space Research (Space Science)

Magneto-telluric inversion

$$J(\mathbf{p}) = R(\mathbf{p}) - \gamma_0 S_0(\mathbf{p})/S_{\max} + \gamma_1 S_1(\mathbf{p})/S_{\max}$$

$$R(\mathbf{p}) = \sum \sum \left[\Phi_{j,m}^{\text{Exp}} - \Phi_{j,k^*,m}^{\text{Mod}}(\mathbf{p}) \right]$$

Outline of problem physical:
 σ - electric conductivity
 Ω^+ - conductive region
 Ω^- - atmosphere



Space Research (Space Science)

Magneto-telluric inversion

$$\sigma^a = 1 \text{ (constant)}$$

$$\sigma_i / \sigma_{\max}$$

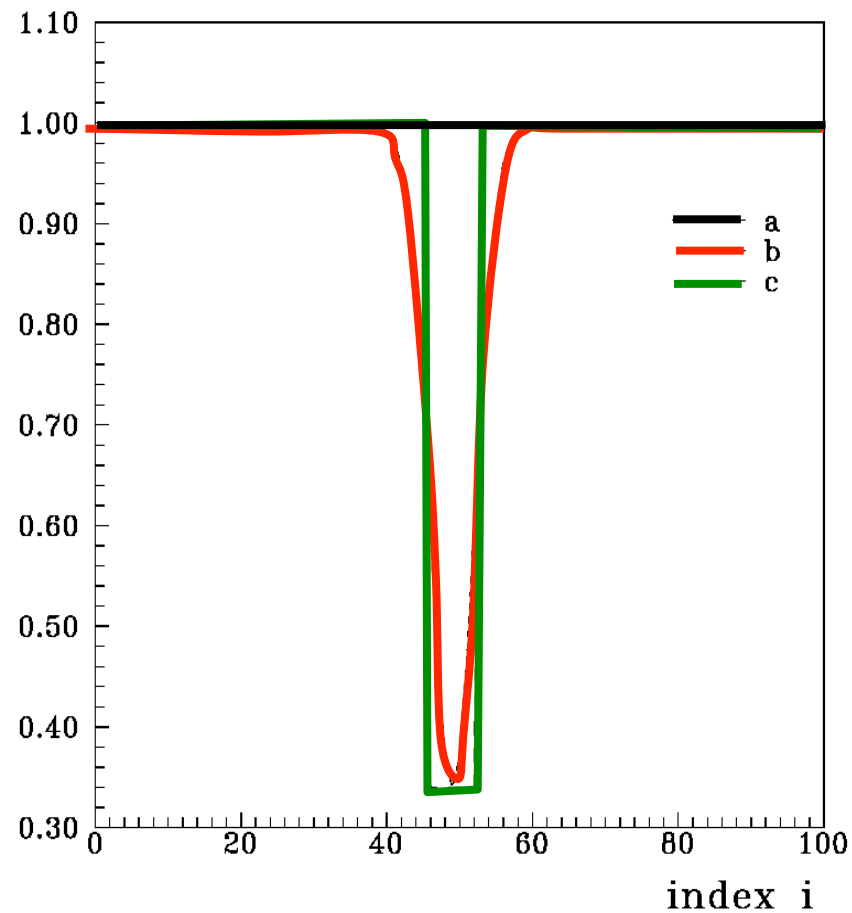
$$\sigma^b = 1 - \left(1/\alpha\sqrt{2}\right) \exp\left[-(x - x_*)^2 / 2\alpha^2\right]$$

$$\sigma^c = \begin{cases} 0.35 & x \in [x_* - \varepsilon, x_* + \varepsilon] \\ 0 & x \in [x_* - \varepsilon, x_* + \varepsilon] \end{cases}$$

$$S_0^a = 1$$

$$S_0^b = 0.9969$$

$$S_0^c = 0.9955$$



Space Research (Space Science)

Magneto-telluric inversion

$$\sigma^a = 1 \text{ (constant)}$$

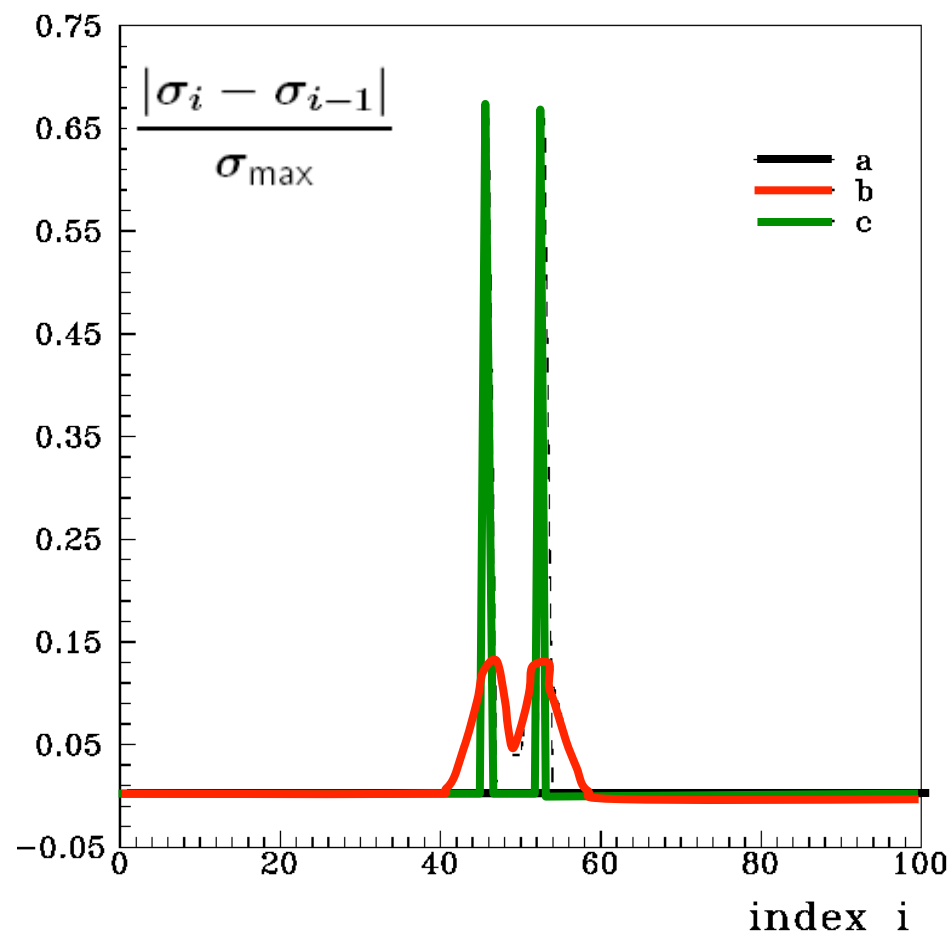
$$\sigma^b = 1 - \left(1/\alpha\sqrt{2}\right)\exp\left[-(x - x_*)^2/2\alpha^2\right]$$

$$\sigma^c = \begin{cases} 0.35 & x \in [x_* - \varepsilon, x_* + \varepsilon] \\ 0 & x \notin [x_* - \varepsilon, x_* + \varepsilon] \end{cases}$$

$$S_1^a = 1.00$$

$$S_1^b = 0.60$$

$$S_1^c = 0.15$$



Space Research (Space Science)

MaxEnt-0: $\gamma_0 \neq 0, \gamma_1 = 0$

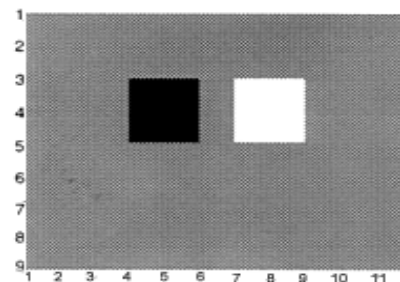
MinEnt-1: $\gamma_0 = 0, \gamma_1 \neq 0$

$$S(u) = \sum_{q=1}^N u_q \log(u_q);$$

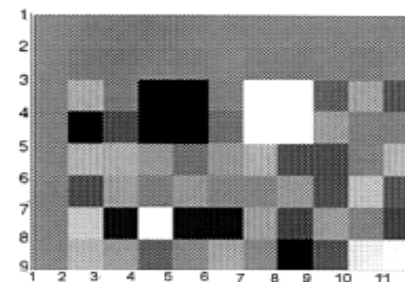
$$u_q = r_q^{(k)} / \sum_{q=1}^N r_q^{(k)};$$

$$r_q^{(k)} = \begin{cases} u_q \\ u_{q+1} - u_q + (u_{\max} - u_{\min}) + \zeta \\ u_{q+1} - 2u_q + u_{q-1} + 2(u_{\max} - u_{\min}) + \zeta \end{cases}$$

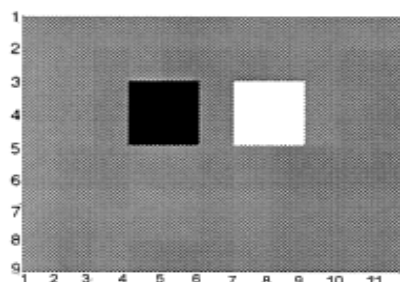
(a) true model



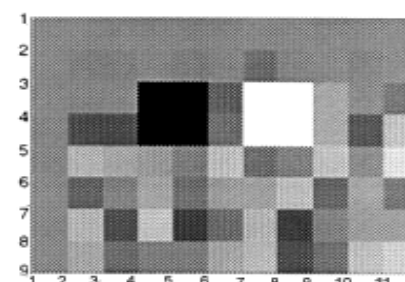
(b) $\gamma_0 = 0, \gamma_1 = 0$



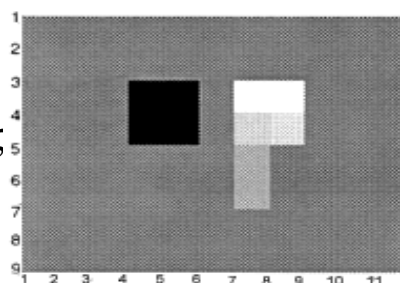
(c) $\gamma_0 = 0, \gamma_1 = 0.03$



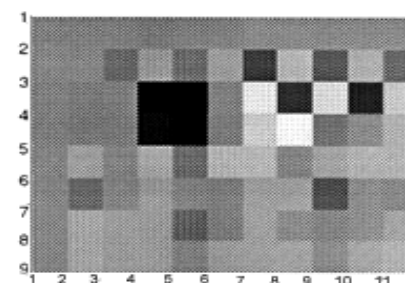
(d) $\gamma_0 = 0.03, \gamma_1 = 0$



(e) $\gamma_0 = 0.03, \gamma_1 = 0.03$

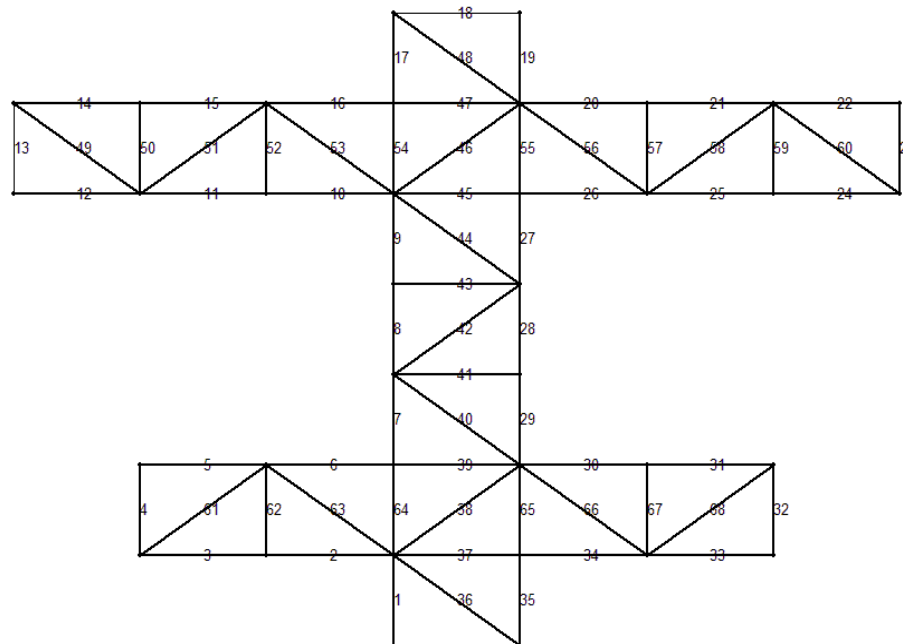


(f) $\gamma_0 = 0.30, \gamma_1 = 0$



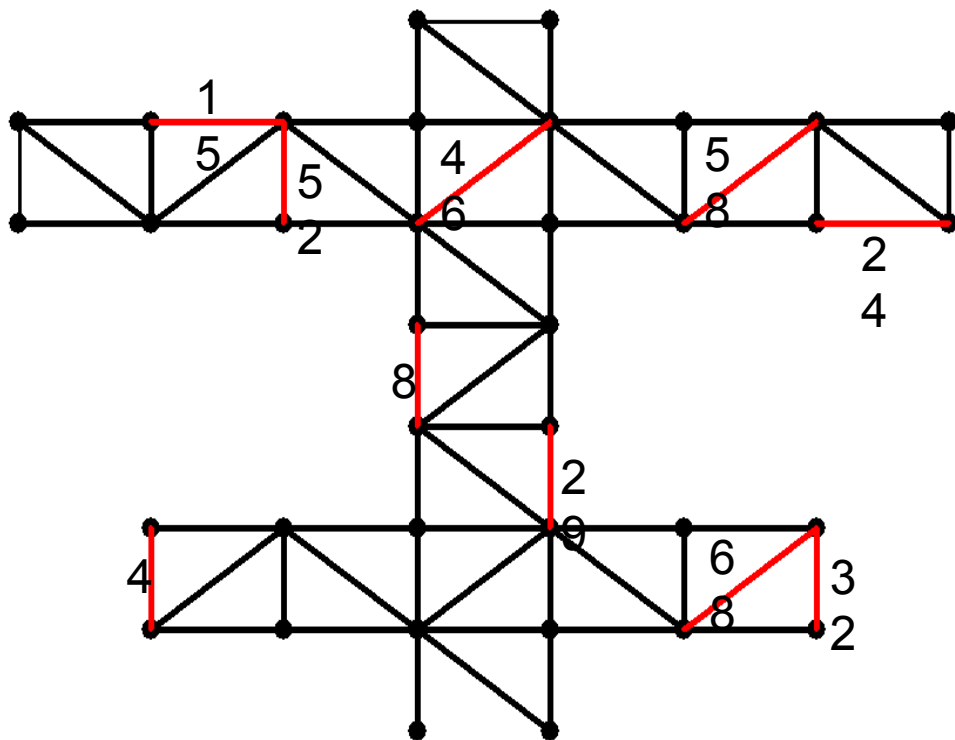
Space Research (Space Engineering)

Damage in aerospace structure



Space Research (Space Engineering)

Damage in aerospace structure



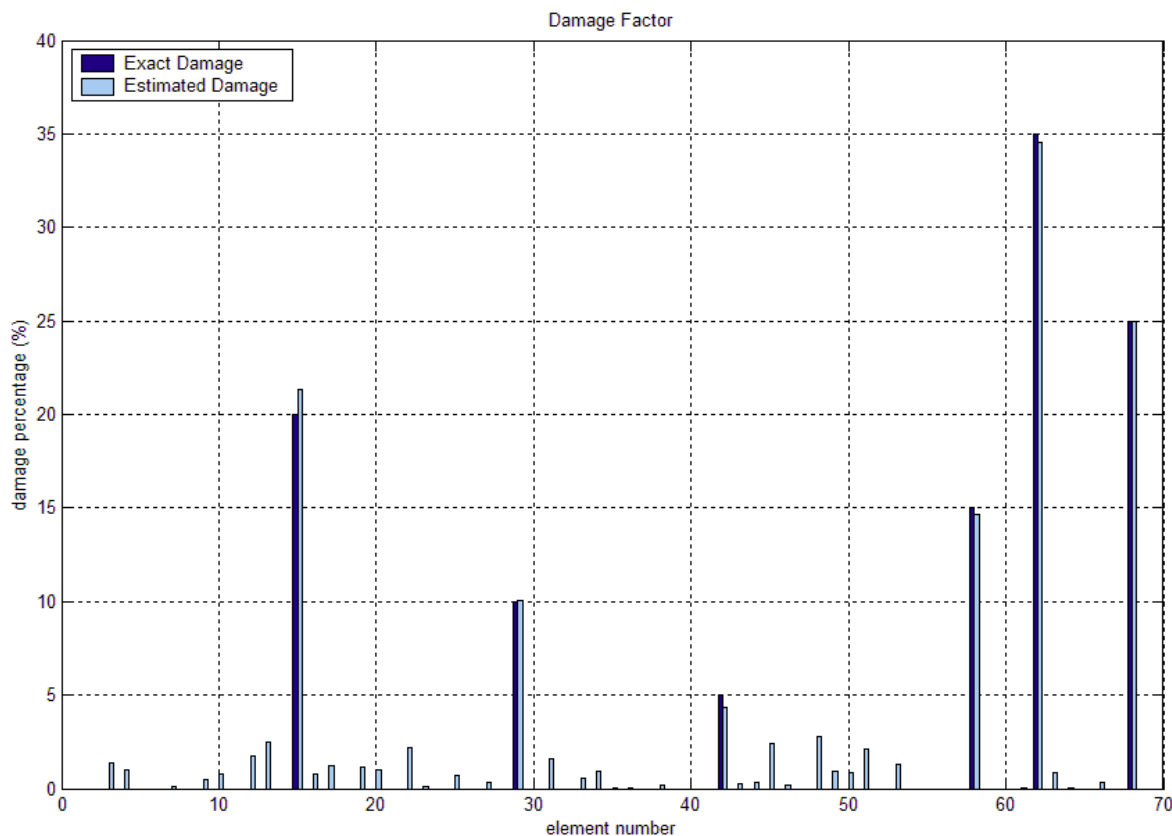
Damage severity:

Element	Damage
8, 24, 46, 68	5%
4, 29, 52	10%
15, 32, 58	15%

Space Research (Space Engineering)

Damage in aerospace structure

Noisy experimental data: $\mathbf{x}^{exp}(t) = \mathbf{x}(t) (1 + \sigma \mathcal{R})$
 $\sigma = 1\%$.



Space Research (Space Engineering)



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Damage assessment of large space structures through the variational approach

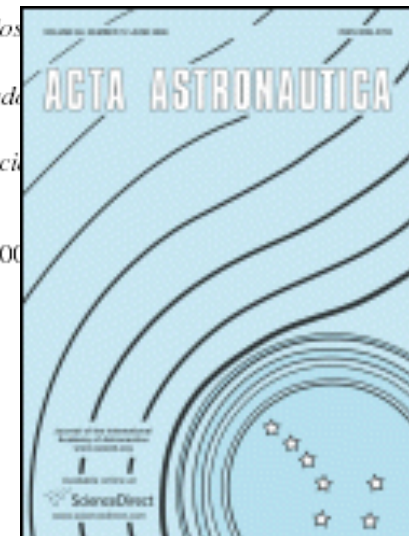
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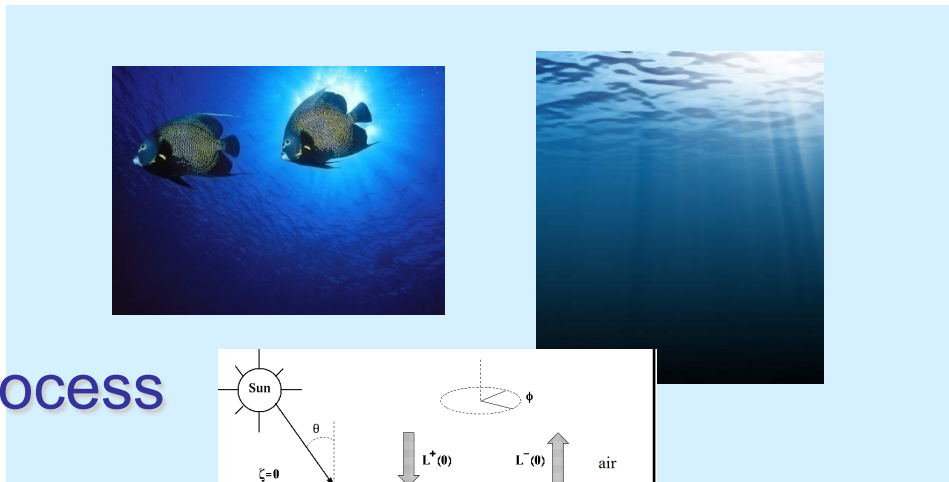
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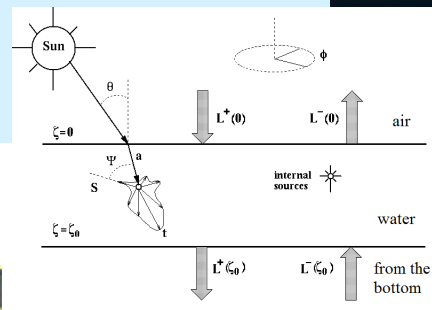
Space Research (oceanography)

Inverse hydrological optics

Hydrologic optics



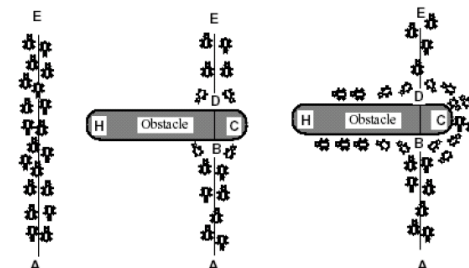
Radiative transfer process



Inverse problem

INVERSE PROBLEMS
INVERSE PROBLEMS

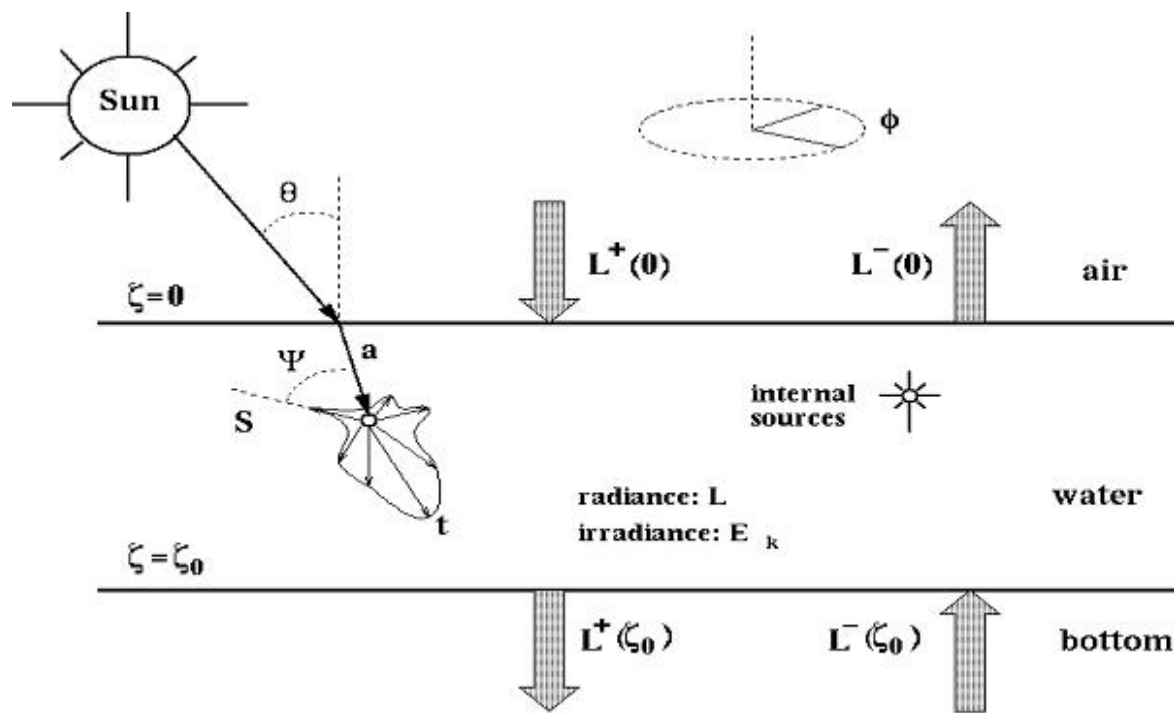
Ant colony optimization



Space Research (oceanography)

Inverse hydrological optics

$$\mu \frac{dL_\lambda(\zeta, \xi)}{d\zeta} + L_\lambda(\zeta, \xi) = \frac{\overbrace{b_\lambda}^{\omega_0}}{a_\lambda + b_\lambda} \iint_{\Xi, \lambda} \beta(\lambda', \xi' \rightarrow \lambda, \xi) d\xi d\lambda + S_\lambda(\zeta, \xi)$$



Space Research (oceanography)

Inverse hydrological optics

Absorption and scattering coefficients:

$$a_{r,g} = \left[a_g^w + 0.06 a_g^c C^{0.65}(z) \right] \left[1 + 0.2 e^{-0.014(\lambda_g - 440)} \right]$$

$$b_{r,g} = \left[550 / \lambda_g \right] 0.30 C^{0.65}(z)$$

Chlorophyll concentration:

$$C(z) = C_0 + \frac{h}{s\sqrt{2\pi}} e^{-1/2[(z-z_{\max})/s]^2}$$

Phase function:
$$p(\cos\Theta) = \frac{1}{4\pi} \frac{1-f^2}{(1+f^2-2f\cos\Theta)^{3/2}}$$

Space Research (oceanography)

Inverse hydrological optics

$$J(\mathbf{p}) = \sum_{k=1}^{N_{\lambda}} \sum_{l=1}^{N_{\xi}} \left[L_{k,l}^{\text{Exp}} - L_{k,l}^{\text{Mod}}(\mathbf{p}) \right]^2 + \alpha \Omega[\mathbf{p}]$$

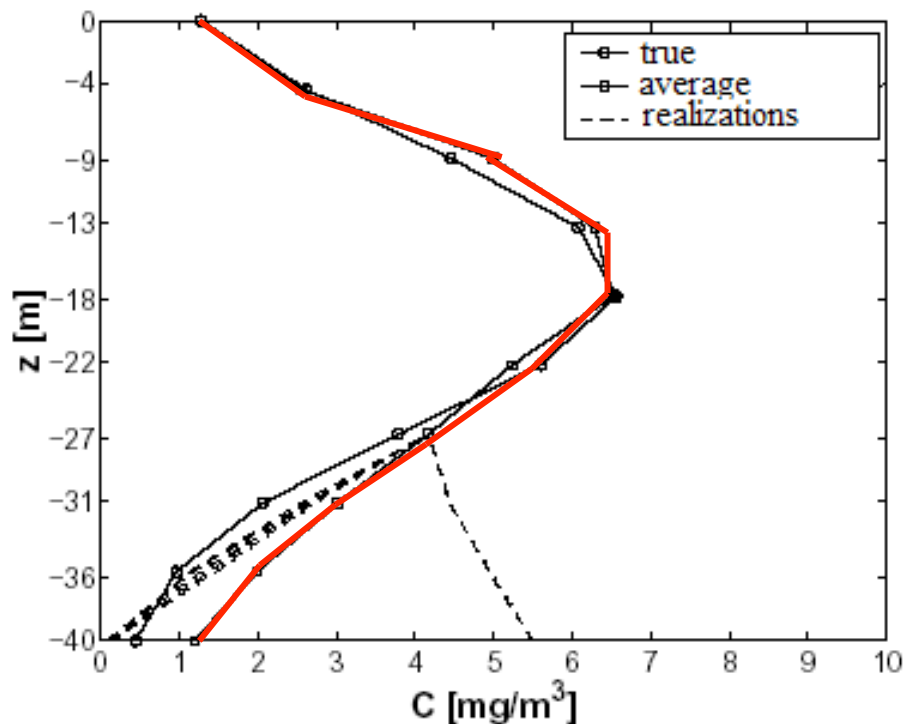
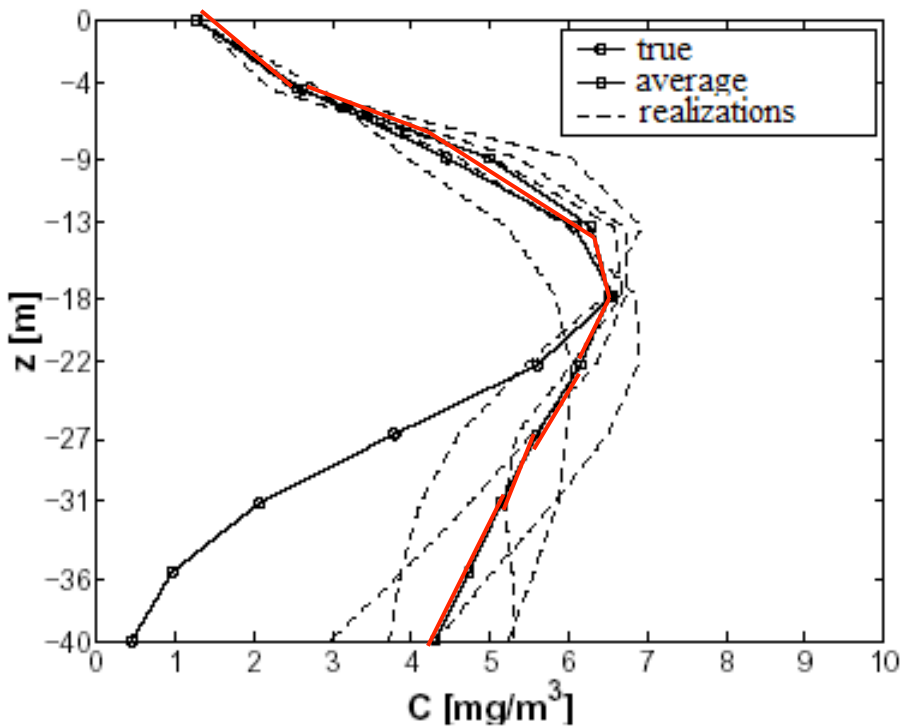
being N_{λ} the number of sensors (satellite channels), N_{ξ} is the number of angle directions and $L_{k,l} = L(\zeta^*, \xi_l, \lambda_k)$, being ζ^* a reference level (water surface).

Preliminar results were obtained with estimation of source terms, where the LTS_N method the modified ant colony system is applied.

Space Research (oceanography)

Inverse hydrological optics

seeds	<i>ns</i>	<i>np</i>	<i>na</i>	<i>mit</i>	ρ	q_0
{17,33,55,81,99}	10	3000	90	500	0.03	0.0



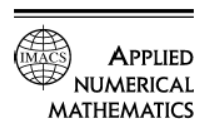
Space Research (oceanography)

Inverse hydrological optics

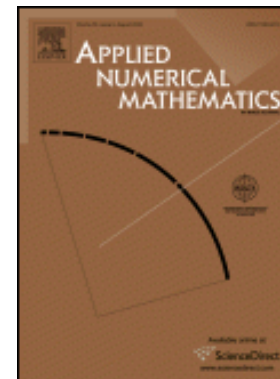


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Applied Numerical Mathematics 47 (2003) 365–376



www.elsevier.com/locate/apnum



Multispectral reconstruction of bioluminescence term
in natural waters

Ezzat S. Chalhoub, Haroldo F. de Campos Velho*

National Institute for Space Research, Laboratory for Computing and Applied Mathematics,
P.O. Box 515, 12245-970 São José dos Campos, SP, Brazil

+ Model

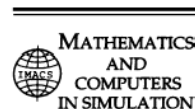
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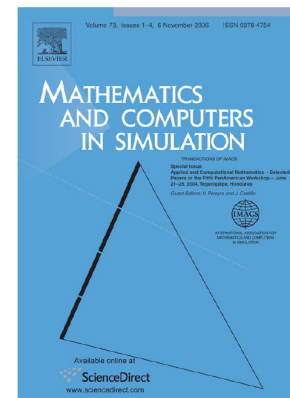
Available online at www.sciencedirect.com



Mathematics and Computers in Simulation xxx (2006) xxx–xxx



www.elsevier.com/locate/matcom



Reconstruction of vertical profiles of the absorption and
scattering coefficients from multispectral radiances

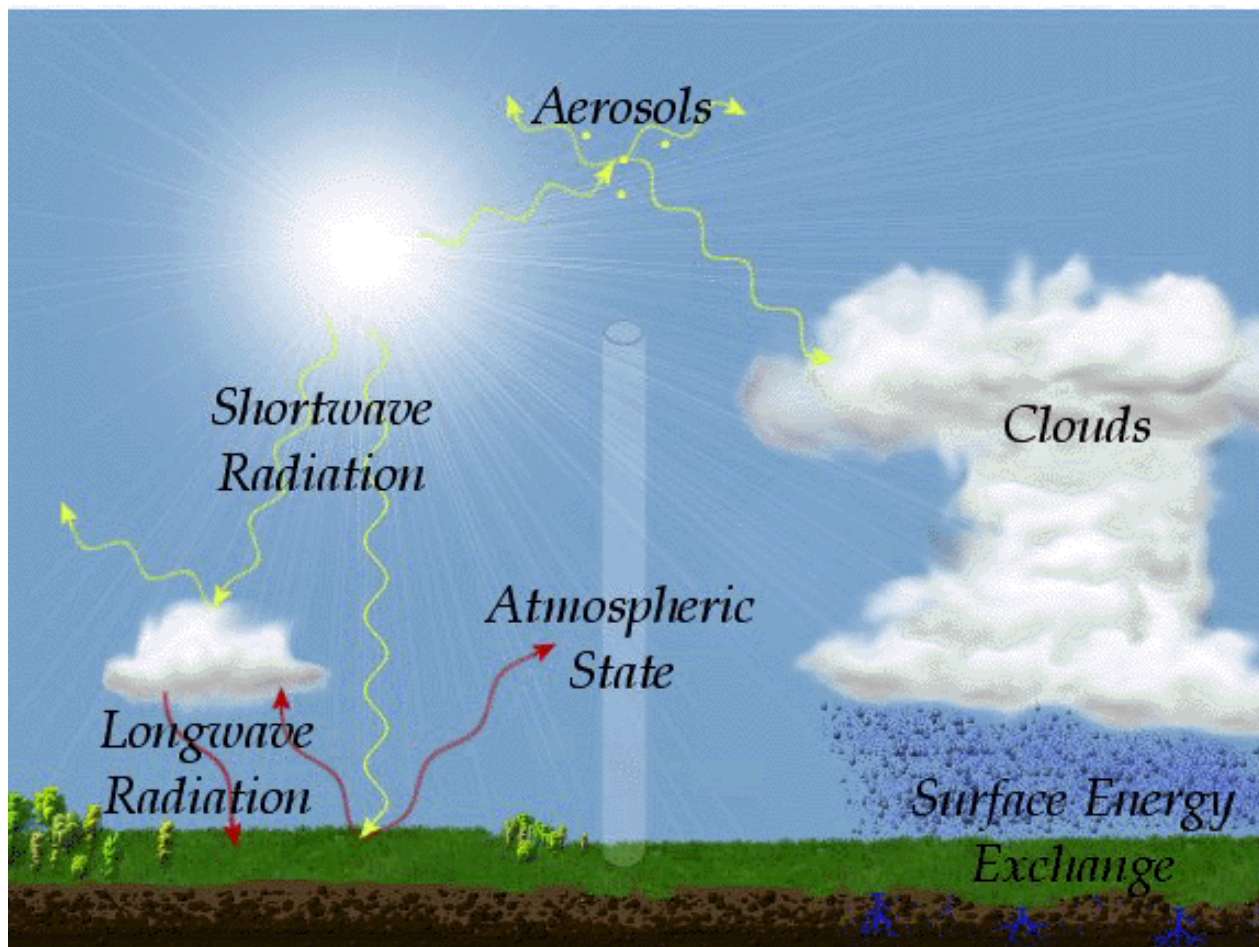
R.P. Souto^{a,*}, H.F. Campos Velho^b, S. Stephany^b

^a Postgraduate Program in Applied Computing (CAP/INPE), INPE—National Institute for Space Research,
PO Box 515, CEP 12245-970 São José dos Campos, SP, Brazil

^b Laboratory for Computing and Applied Mathematics (LAC/INPE), INPE—National Institute for Space Research,
PO Box 515, CEP 12245-970 São José dos Campos, SP, Brazil

Space Research (meteorology)

Atmospheric temperature from satellite data



Space Research (meteorology)

Atmospheric temperature from satellite data

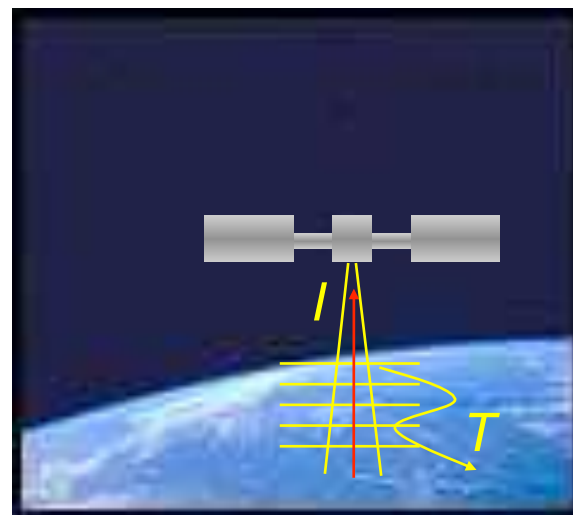
$$\tilde{I}_\lambda(\tau_\lambda) = I_\lambda(\tau_\lambda) - I_\lambda(\tau_\lambda^{(s)}) = - \int_{\tau_\lambda^{(s)}}^{\tau_\lambda} B_\lambda(\tau_\lambda) d\tau_\lambda$$

$$B_\lambda(T) = \frac{2h\lambda^3}{c^2 \left[e^{h\lambda/(KT)} - 1 \right]} \quad (\text{Planck function})$$

$I_\lambda(\tau_\lambda^{(s)})$: radiation intensity emitted from the earth's surface

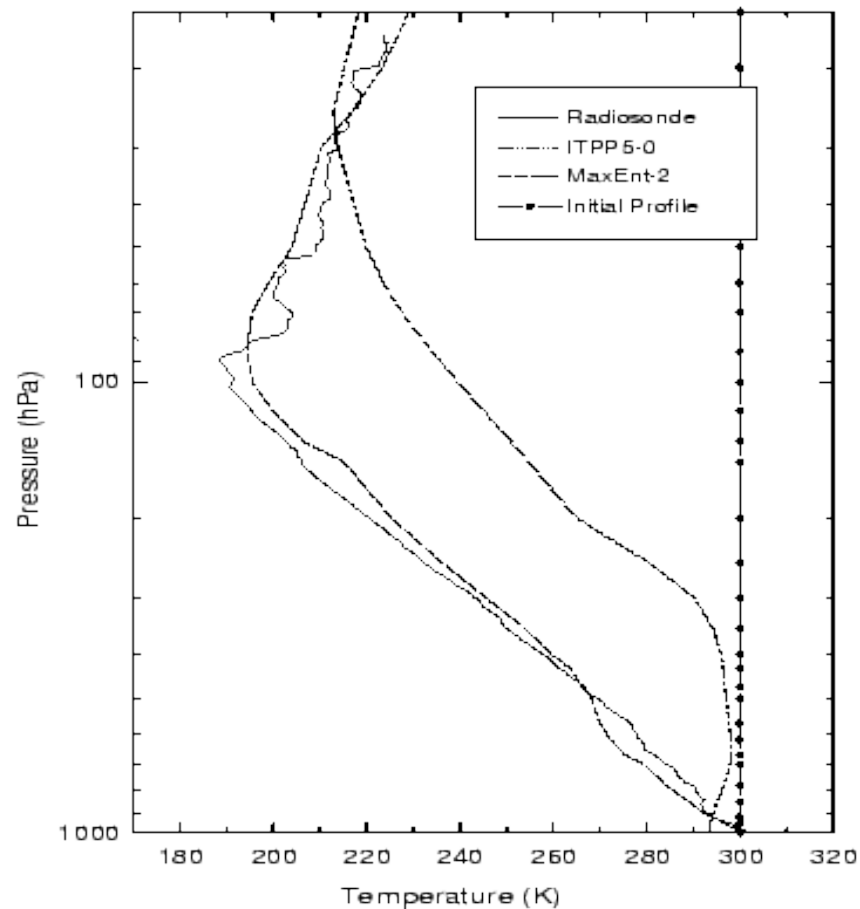
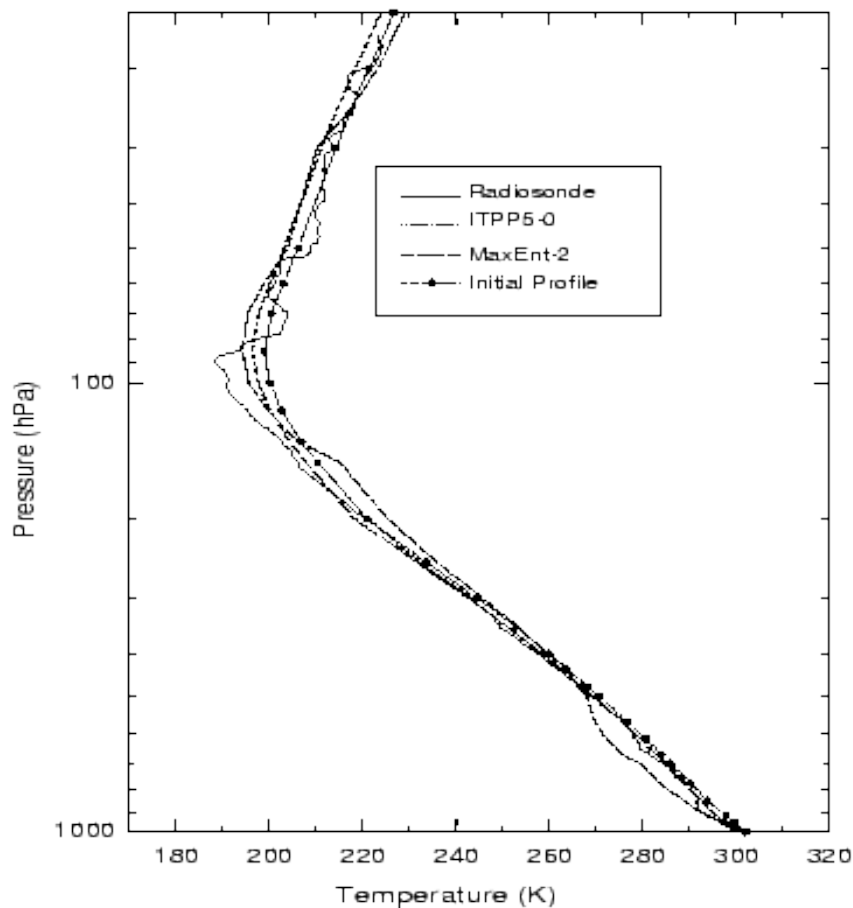
$\tau_\lambda(z)$: vertical transmittance from height z

$T(z)$: vertical temperature profile



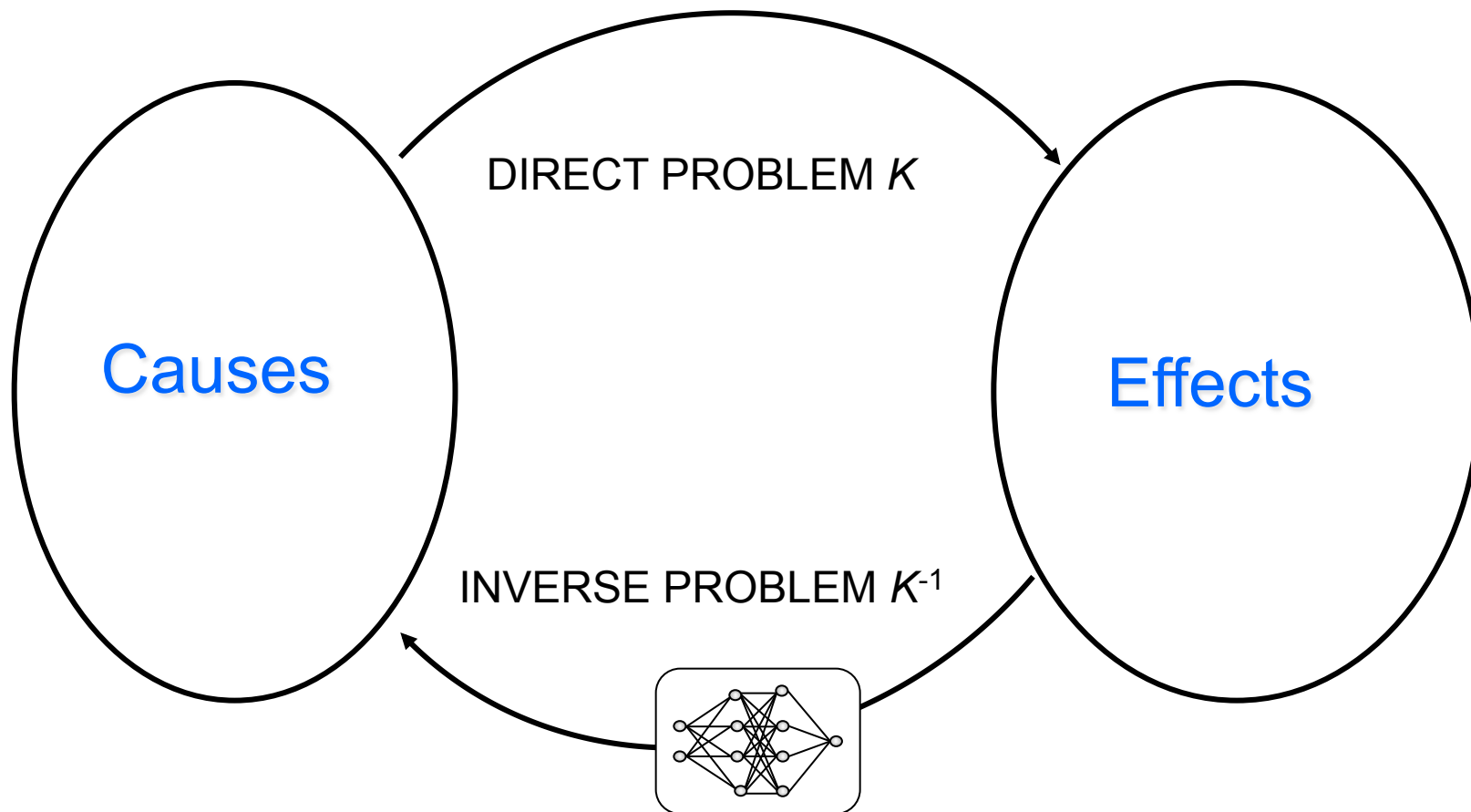
Space Research (meteorology)

Regularization: 2n order entropy



Inverse problems

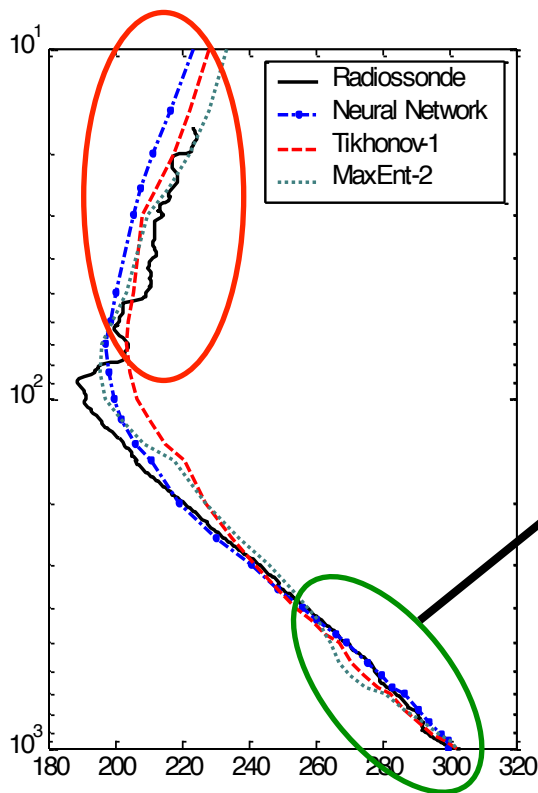
Neural networks for inverse problems



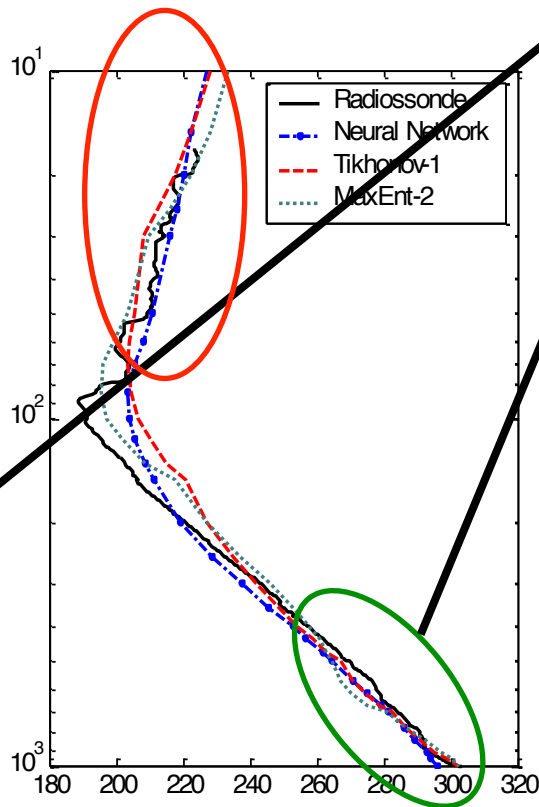
Space Research (meteorology)

Atmospheric temperature

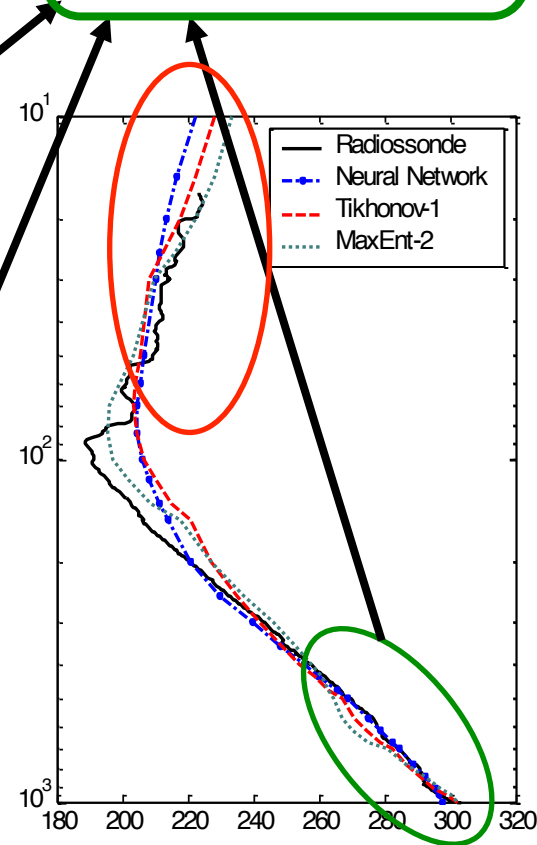
More important for numerical weather prediction



Retrievals using SDB1 for training phase.



Retrievals using TIGR for training phase.



Retrievals combining SDB1+TIGR.

Space Research (meteorology)

Atmospheric temperature from satellite data

Neurocomputers: implemented by FPGA

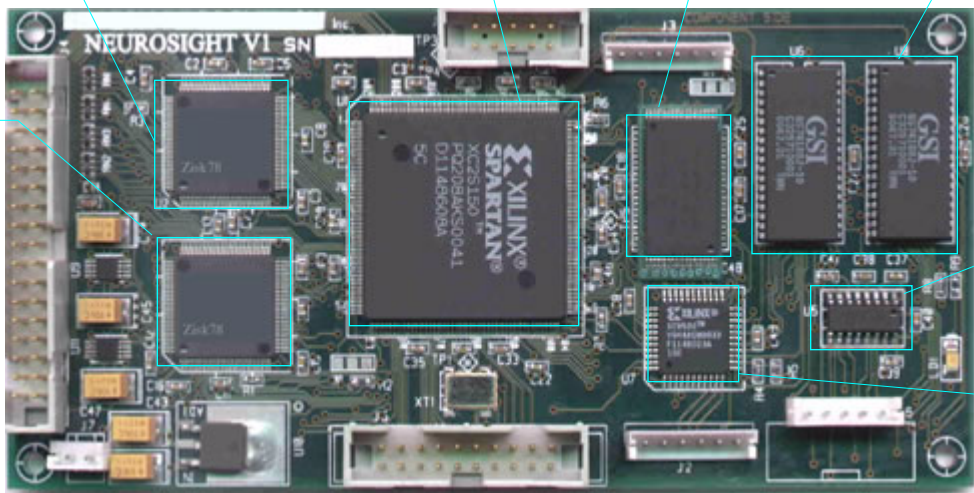
ZISC78_1

ZISC78_2

FPGA

E²PROM

Memory RAM

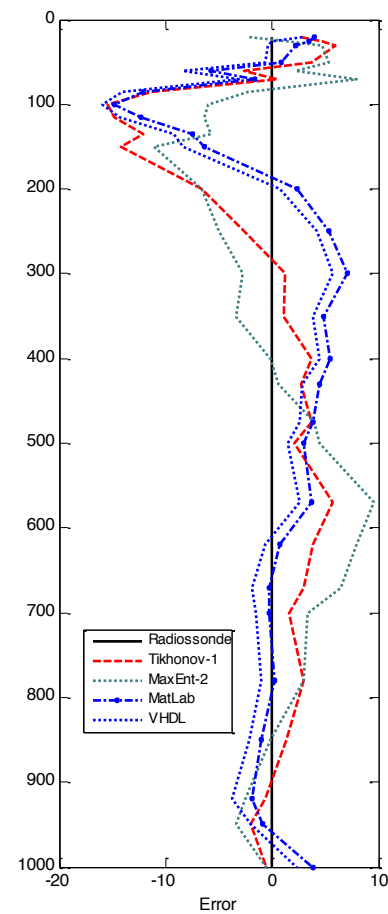
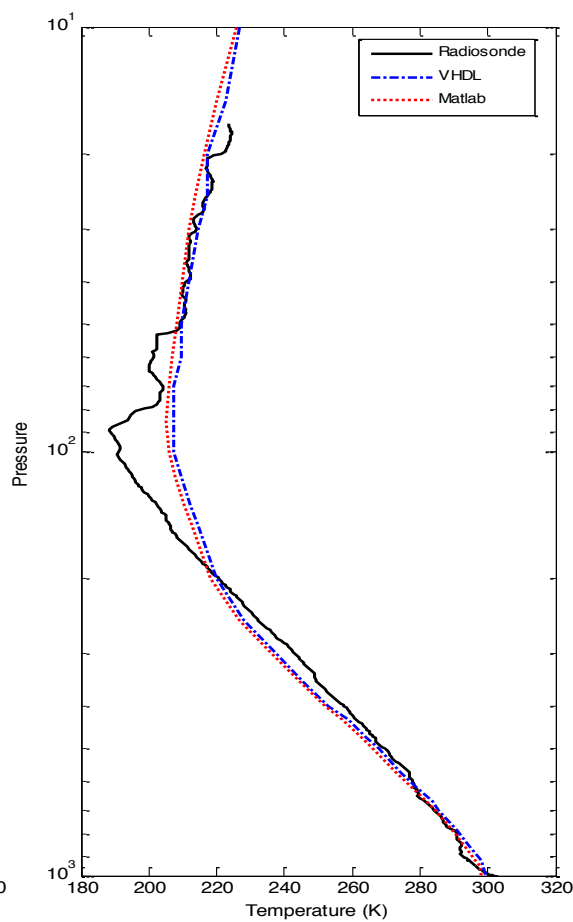
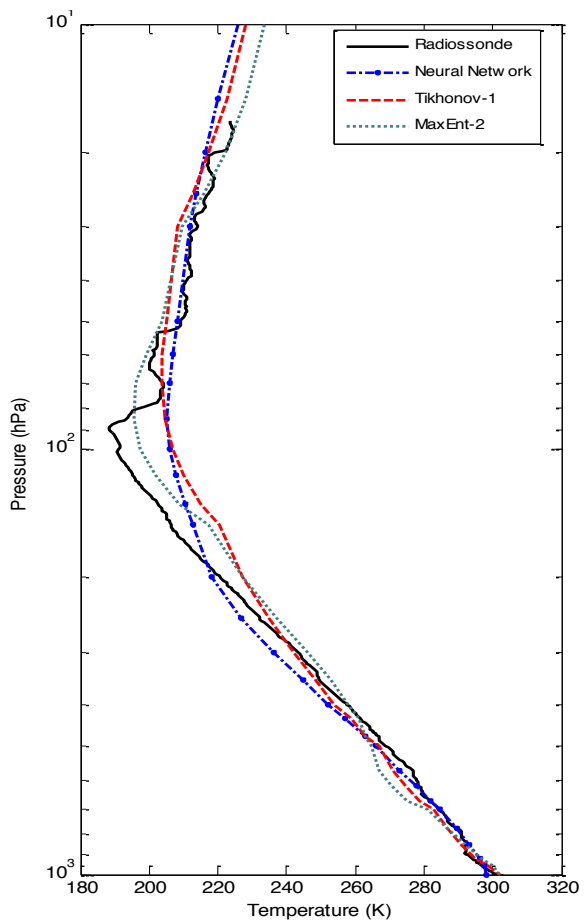


S_I/O

CLP

Space Research (meteorology)

Atmospheric temperature from satellite data



Atmospheric temperature retrieval using a Radial Basis Function Neural Network

E.H. Shiguemori

Laboratório Associado de Computação e Matemática Aplicada – LAC,
Instituto Nacional de Pesquisas Espaciais – INPE,
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Agência Nacional de Águas – ANA, Brasília, DF, Brazil
E-mail: joao.carvalho@ana.gov.br



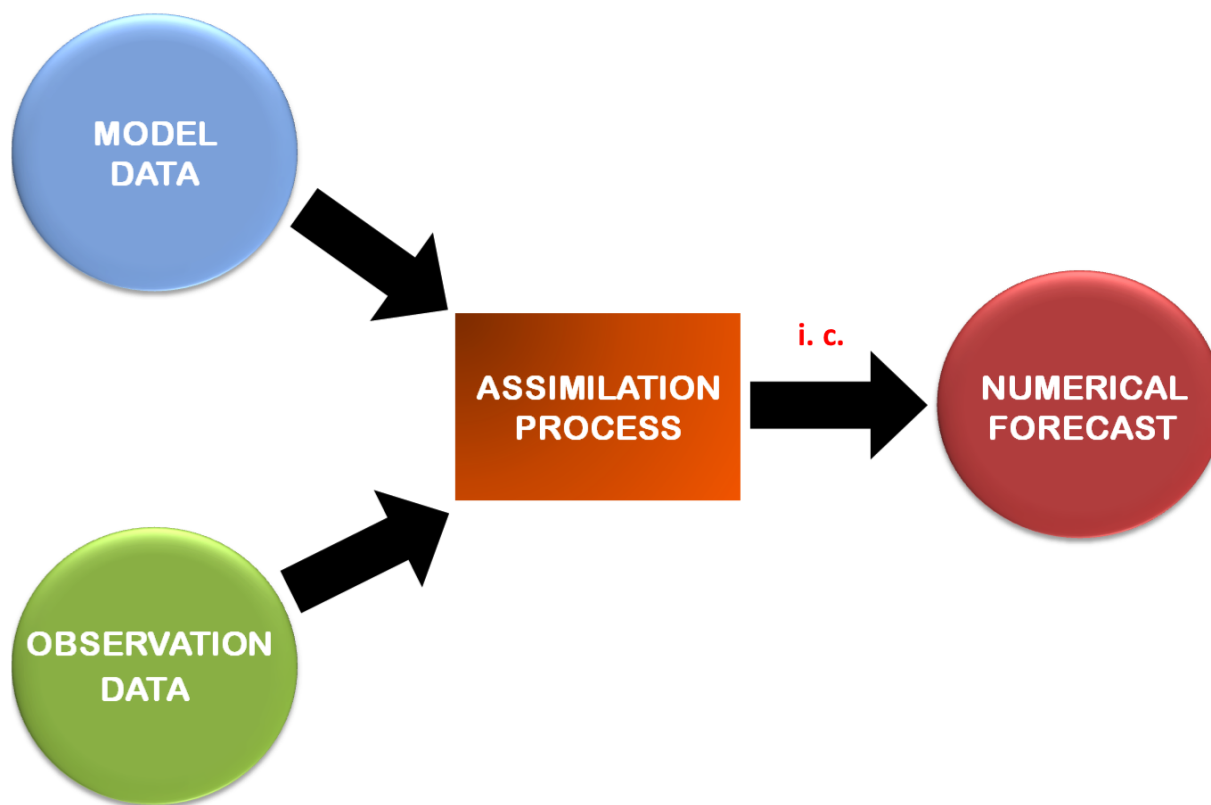
Space Research (meteorology)

Data assimilation: finding initial condition



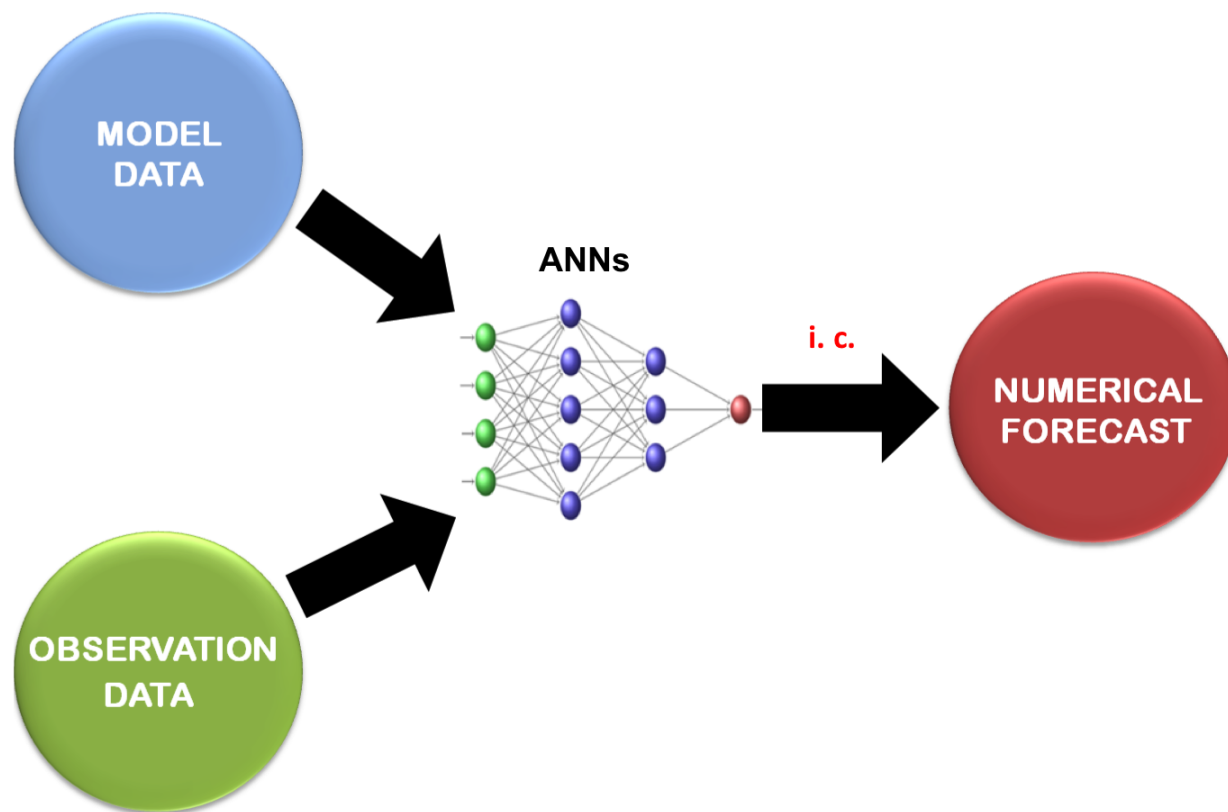
Space Research (meteorology)

Data assimilation: finding initial condition



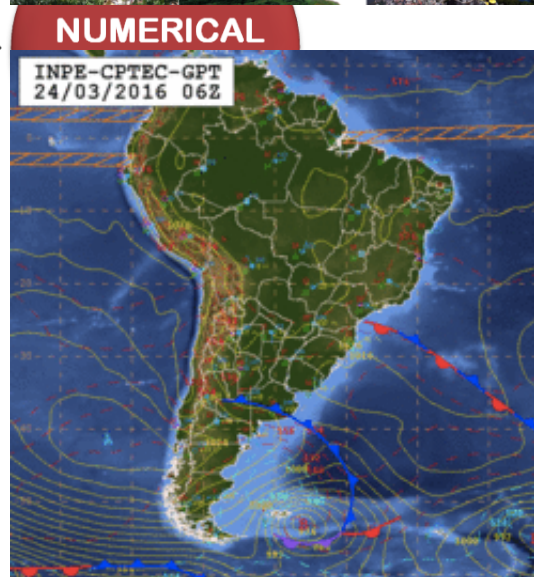
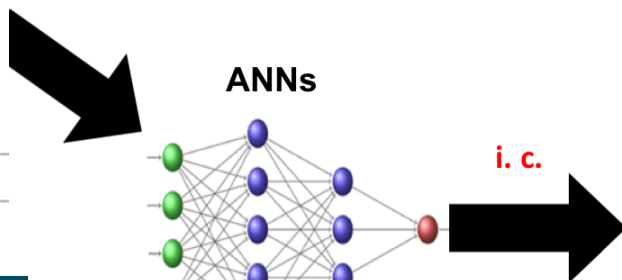
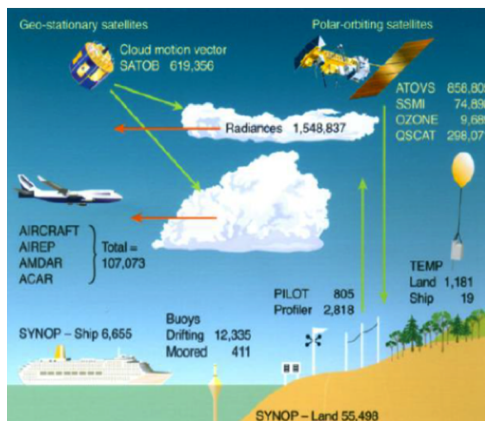
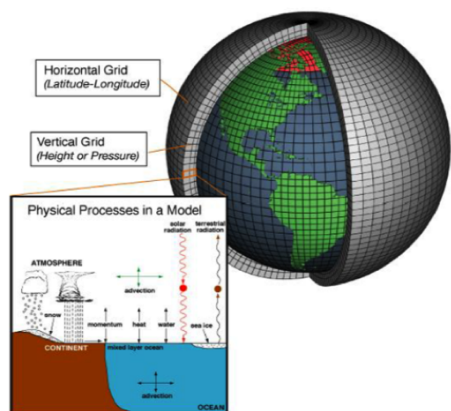
Space Research (meteorology)

Data assimilation: finding initial condition



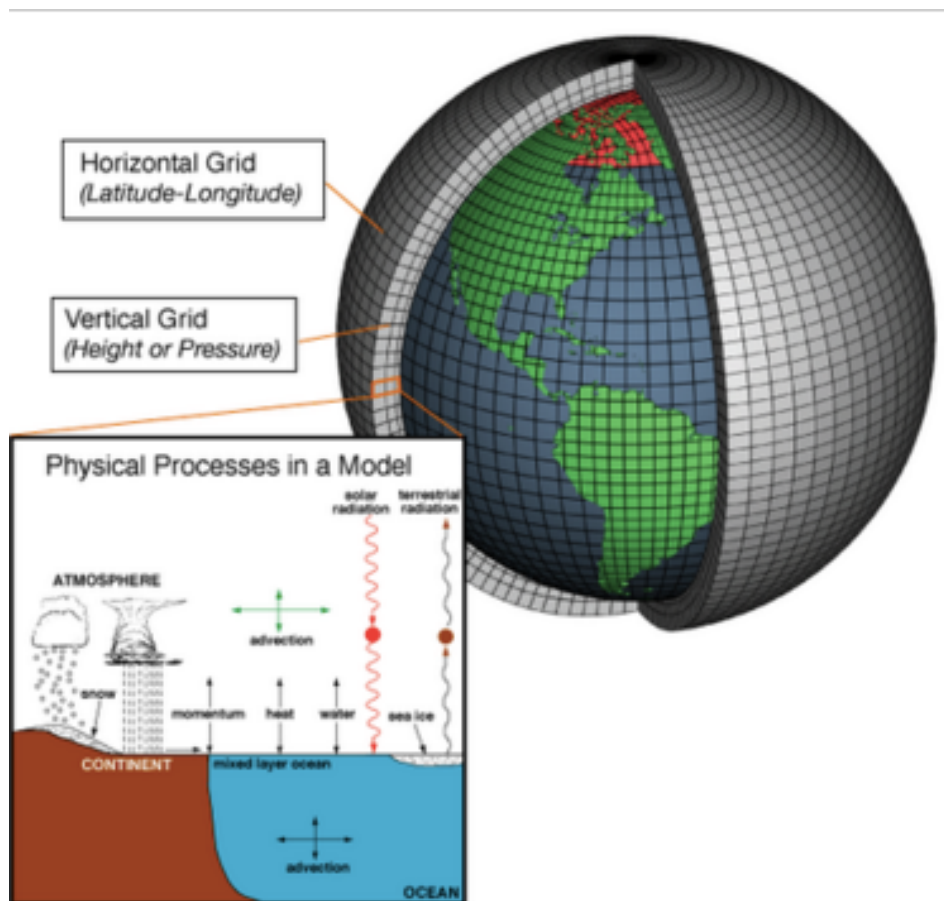
Space Research (meteorology)

Data assimilation: finding initial condition



PART 2 – Applications to Space Research

- Numerical Weather Prediction
- Relevant and computer intensive simulation

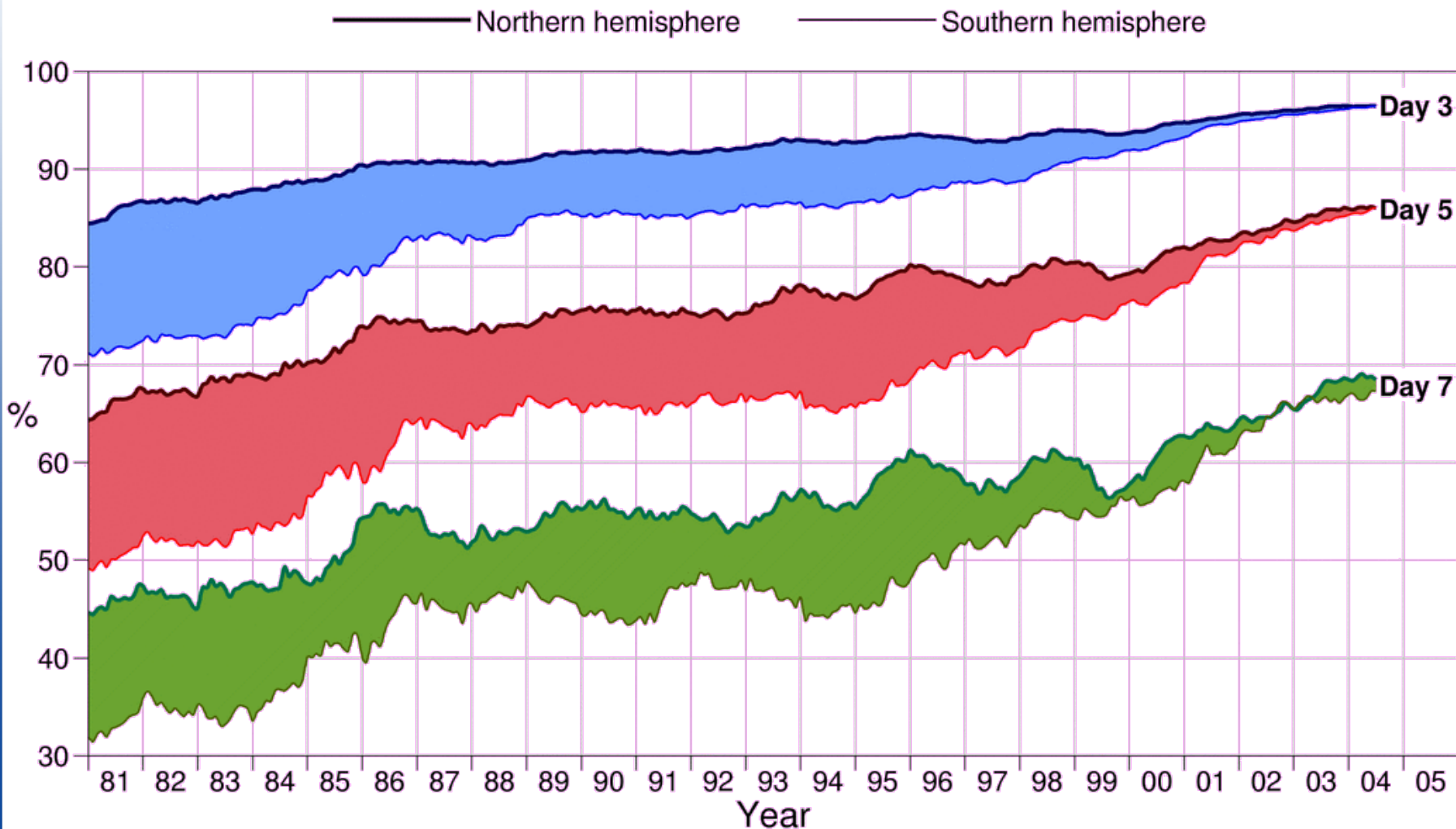




Forecasts Scores

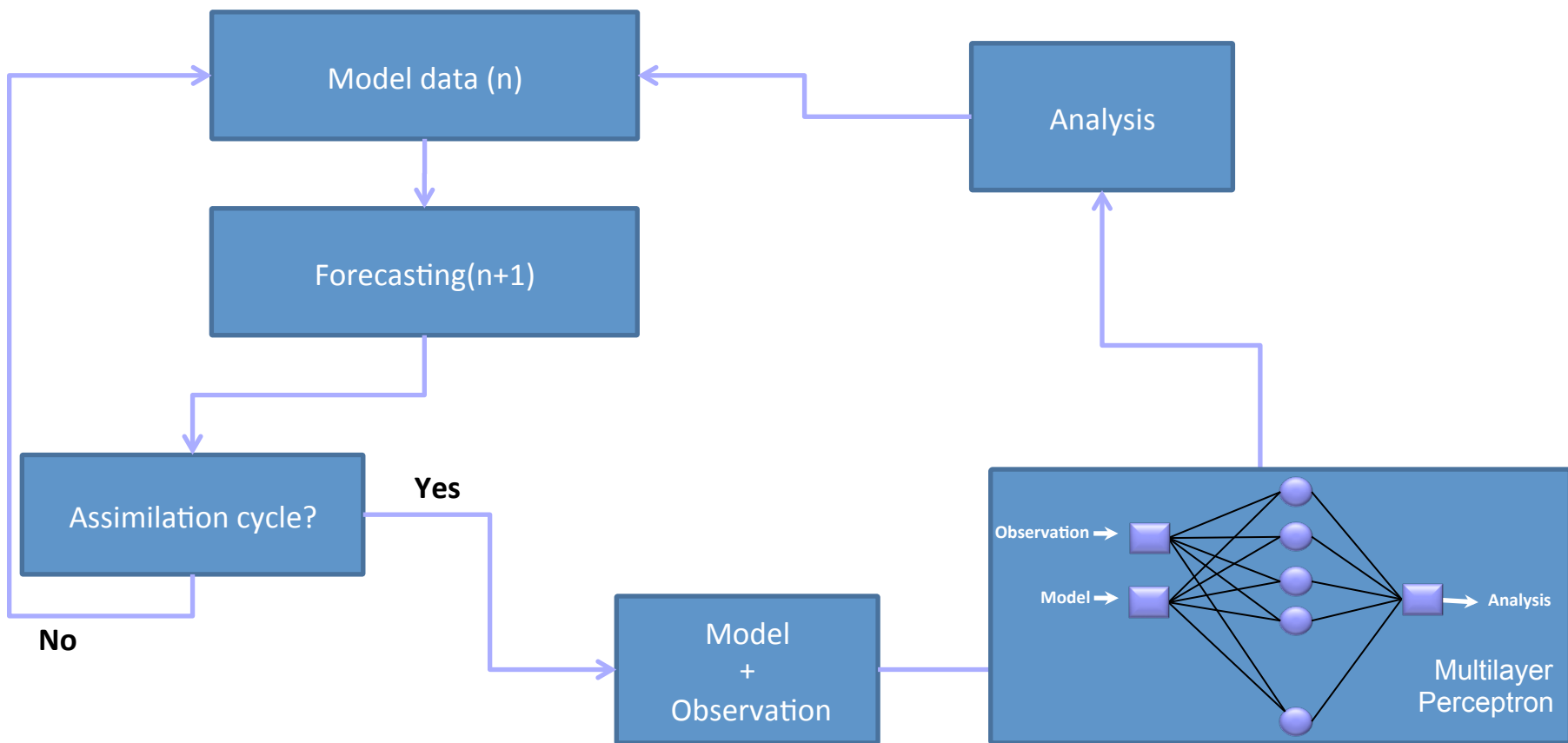
ECMWF

Anomaly correlation of 500hPa height forecasts



Space Research (meteorology)

Data assimilation: finding initial condition



Space Research (meteorology)

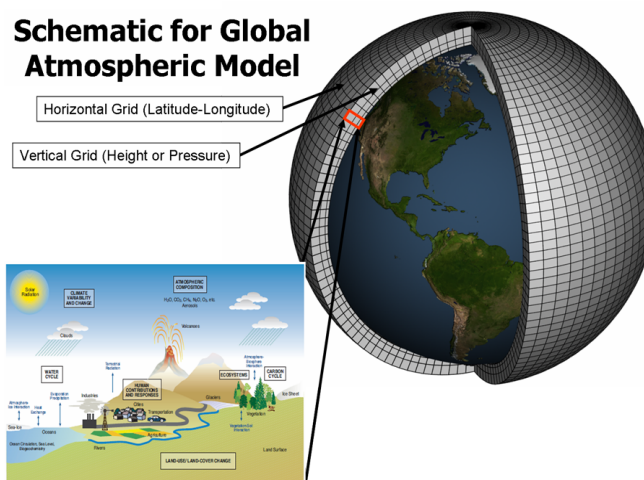
Data assimilation: finding initial condition

FSUGSM

(Florida State University global spectral model)

~ regular grid $96 \times 192 \times 27$

Schematic for Global Atmospheric Model



Globe divided into 4 horizontal and 6 vertical sub-domains (regions), with different neural network for each meteorological variable:

neural networks: $4 \times 6 \times 6 = 144$ networks.

How can we do that?

Other applications with MPCA



- **Inverse Problem:**

Automatic configuration for neural network applied to atmospheric temperature profile identification.

INTERNATIONAL CONFERENCE ON ENGINEERING OPTIMIZATION, 2012.



imse 2014 

- **Inverse Problem:**

MPCA for solving an inverse radiative problem.

IIMSE – INTEGRAL METHODOS IN SCIENCE AND ENGINEERING, 2014



- **Climate Prediction:**

MPCA meta-heuristics for automatic architecture optimization of a supervised artificial neural network.

10th WORLD CONGRESS ON COMPUTATIONAL MECHANICS, 2012.



- **Data Assimilation:**

MPCA meta-heuristics for automatic architecture optimization of a supervised artificial neural network.

2nd CONFERENCE ON UNCERTANTIES, 2014.

PART 2 – Applications to Space Research

▪ Numerical Weather Prediction: equations

Movement Equation (*momentum*)

$$\frac{du}{dt} - fv + \frac{1}{\rho} \frac{\partial p}{\partial x} = 0$$

$$\frac{dh}{dt} + g + \frac{1}{\rho} \frac{\partial p}{\partial z} = 0$$

$$\frac{dv}{dt} + fu + \frac{1}{\rho} \frac{\partial p}{\partial y} = 0$$

Continuity Equation (*mass*)

$$\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x} (\rho u) + \frac{\partial}{\partial y} (\rho v) + \frac{\partial}{\partial z} (\rho h) = 0$$

Thermodynamic equation (*energy*)

$$p = f(T)\rho \Rightarrow \frac{f(T)}{T} = \frac{g(\rho)}{\rho} \equiv R(cte) \quad p = g(\rho)T$$

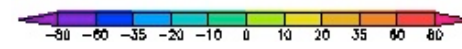
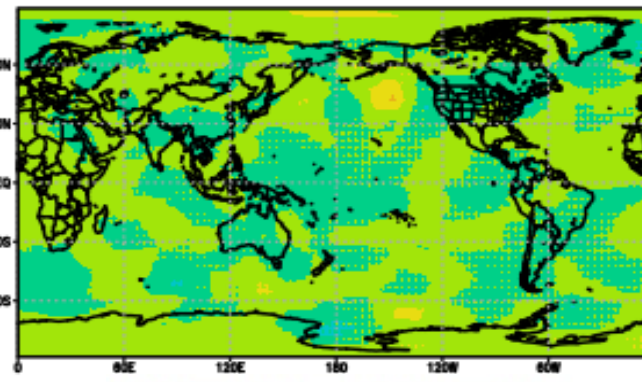
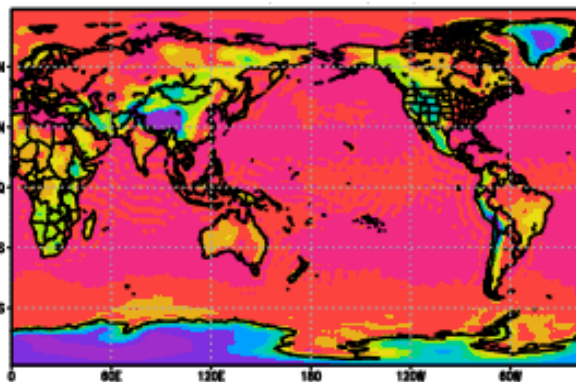
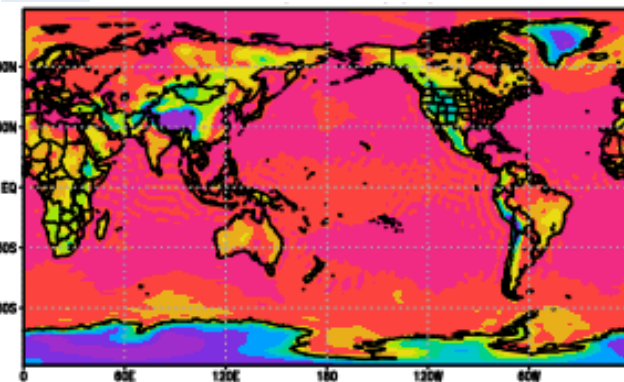
$$p = \rho RT$$

$$C_v \frac{dT}{dt} + p_{55} \frac{d(1/\rho)}{dt} = \frac{dq}{dt}$$

Space Research (meteorology)

Surface Pressure(Kg/Kg) generalization

04/Jan/2005 – 12 UTC



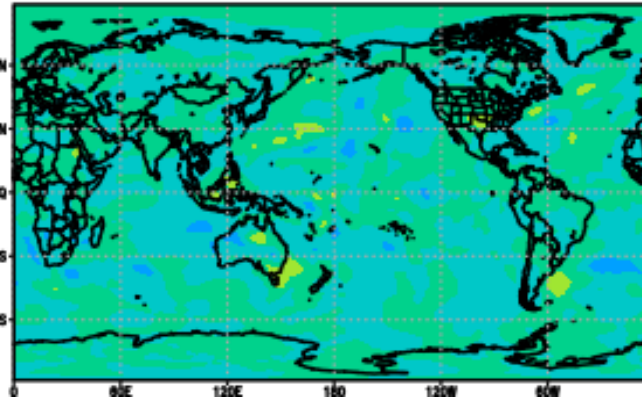
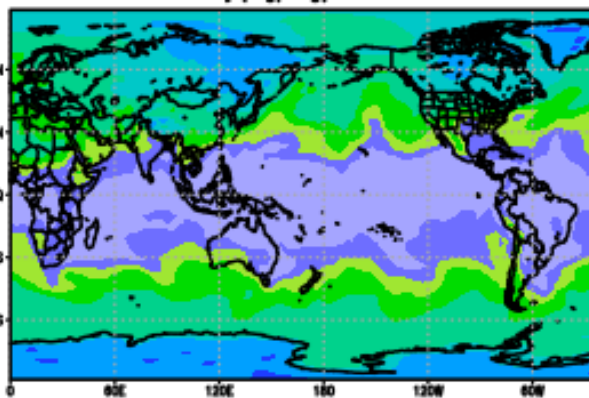
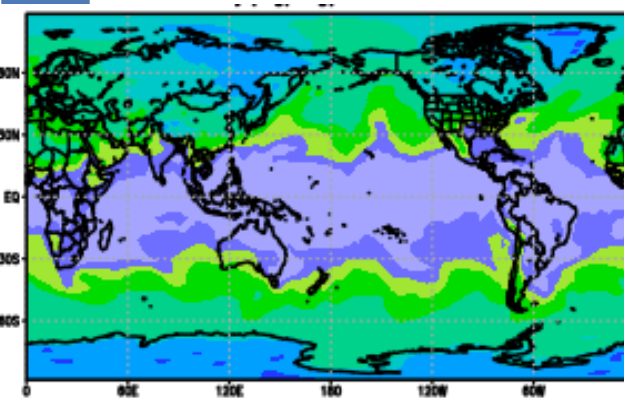
LETKF analysis

MLP analysis

Differences analysis

Specific Humidity (Kg/Kg) generalization

04/Jan/2005 – 12 UTC



LETKF analysis

MLP analysis

Differences analysis

Space Research (meteorology)

Data assimilation: finding initial condition

Execution of 124 cycles	MLP-DA (hour:min:sec)	LETKF (hour:min:sec)	
Analysis time	00:02:29	11:01:20	← 266 times faster
Ensemble time	00:00:00	15:50:40	
Parallel model time	00:27:20	00:00:00	
Total Time	00:29:49	26:52:00	← 55 times faster

Data assimilation: an essential issue

- **Neural networks: Elman and Jordan ANN**

Revista Brasileira de Meteorologia, v.20, n.3, 411-420, 2005

REDES NEURAIS RECORRENTES TREINADAS COM CORRELAÇÃO CRUZADA APLICADAS A ASSIMILAÇÃO DE DADOS EM DINÂMICA NÃO-LINEAR

FABRÍCIO PEREIRA HÄRTER e HAROLDO FRAGA DE CAMPOS VELHO



MINISTÉRIO DA CIÊNCIA E TECNOLOGIA
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Data assimilation: an essential issue

- Neural networks: Shallow water equation (RBF-NN)



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Applied Mathematical Modelling 32 (2008) 2621–2633

APPLIED
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New approach to applying neural network in nonlinear dynamic model

Fabrício P. Härter *, Haroldo Fraga de Campos Velho

Instituto Nacional de Pesquisas Espaciais, Laboratório Associado de Computação e Matemática Aplicada, São José dos Campos, SP, Brazil

Received 2 January 2007; received in revised form 31 July 2007; accepted 17 September 2007

Available online 30 October 2007



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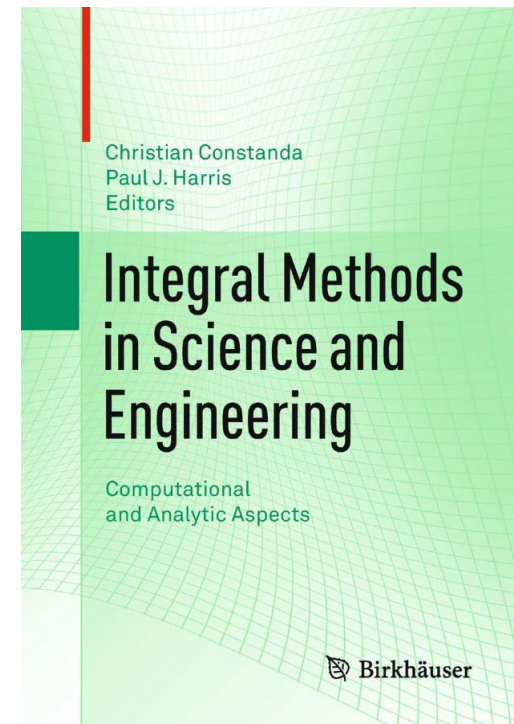
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Data assimilation: an essential issue

Adaptive Particle Filter for Stable Distribution

H.F. de Campos Velho and H.C. Morais Furtado



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Data assimilation: an essential issue

IOPscience

iopscience.iop.org

6th International Conference on Inverse Problems in Engineering: Theory and Practice

IOP Publishing

Journal of Physics: Conference Series **135** (2008) 012073

doi:10.1088/1742-6596/135/1/012073

Data assimilation: particle filter and artificial neural networks

Helaine Cristina Morais Furtado,
Haroldo Fraga de Campos Velho,
Elbert Einstein Nehrer Macau

Data assimilation: an essential issue

IOPscience

iopscience.iop.org

Dynamic Days South America 2010

IOP Publishing

Journal of Physics: Conference Series **285** (2011) 012036

doi:10.1088/1742-6596/285/1/012036

Neural networks for emulation variational method for data assimilation in nonlinear dynamics

Helaine C. Morais Furtado

Haroldo F. de Campos Velho

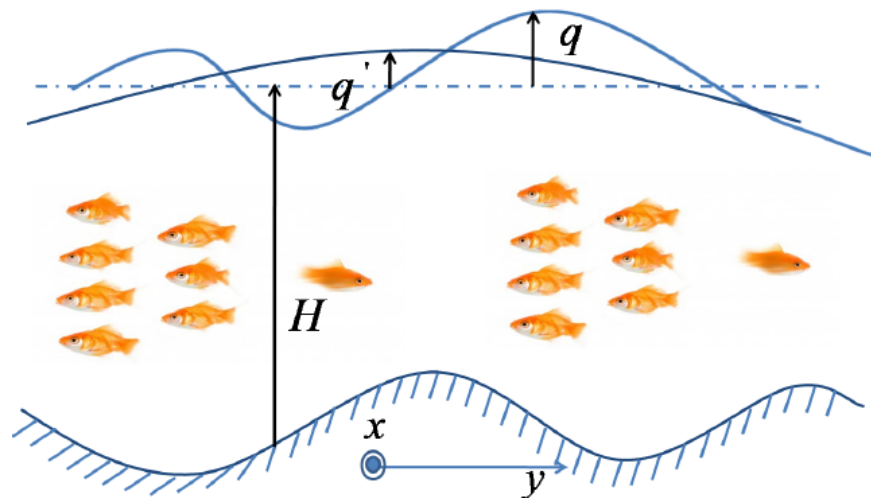
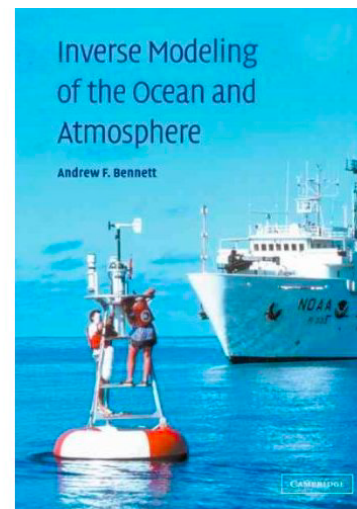
Elbert E. Macau

Shallow water 2D for ocean circulation

$$\frac{\partial u}{\partial t} - fv + g \frac{\partial q}{\partial x} + r_u u = F_u$$

$$\frac{\partial v}{\partial t} + fu + g \frac{\partial q}{\partial y} + r_v v = F_v$$

$$\frac{\partial q}{\partial t} + H \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + r_q q = 0$$





Obrigado!